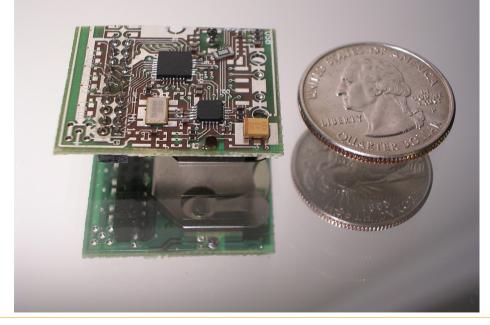
### Experimenting with the PIP Radio Platform

#### Presented by Ben Firner



### A PIP is a small radio device

- Affectionately called a "Pipsqueak"
- Runs on a coin cell battery
- PIP = Persistent Identification Packets





### PIPs are a flexible test platform

- There is a very low barrier to entry
  - Code is in C (assembly can be used as well)
- We have already written the hard parts
  USB code on the PIP and on Linux readers
- Well set up to test power consumption
- The best way to learn about radio is to use it



# Things you can observe directly

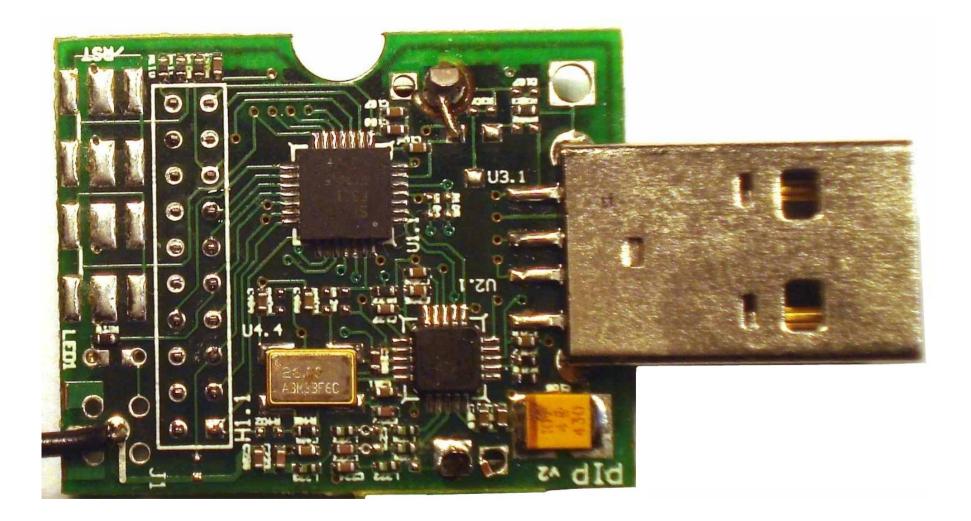
- RSSI
- Power consumption using the oscilloscope
- View packet formats and spectrum on the network analyzer
  - CC1100 does FSK, GFSK, MSK, and ASK/OOK
- Use the vector signal analyzer to get raw packet data



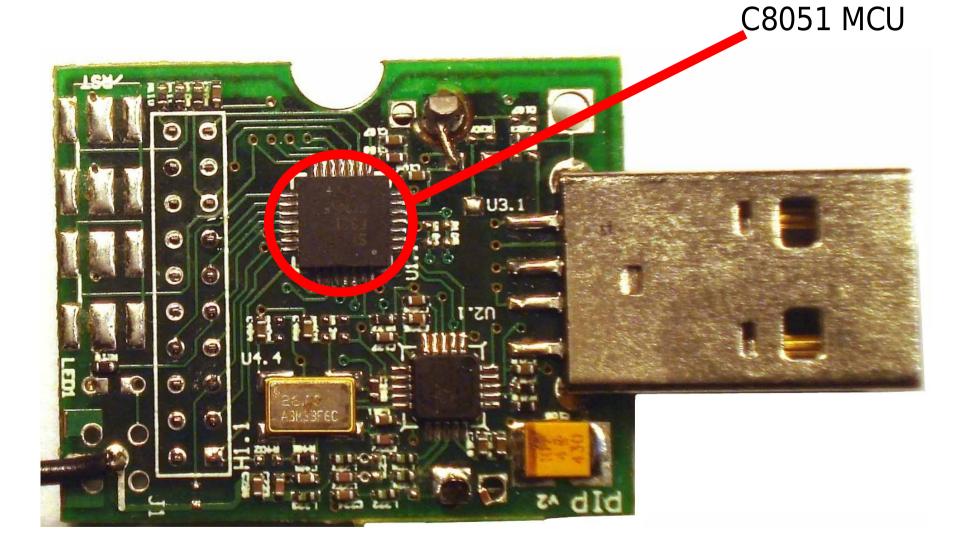
### Statistics you can gather

- Packet loss
  - How well does radio work from car to car?
- Interference
  - Should you have your router next to your microwave?
- Signal attenuation
  - Are tinfoil hats effective?

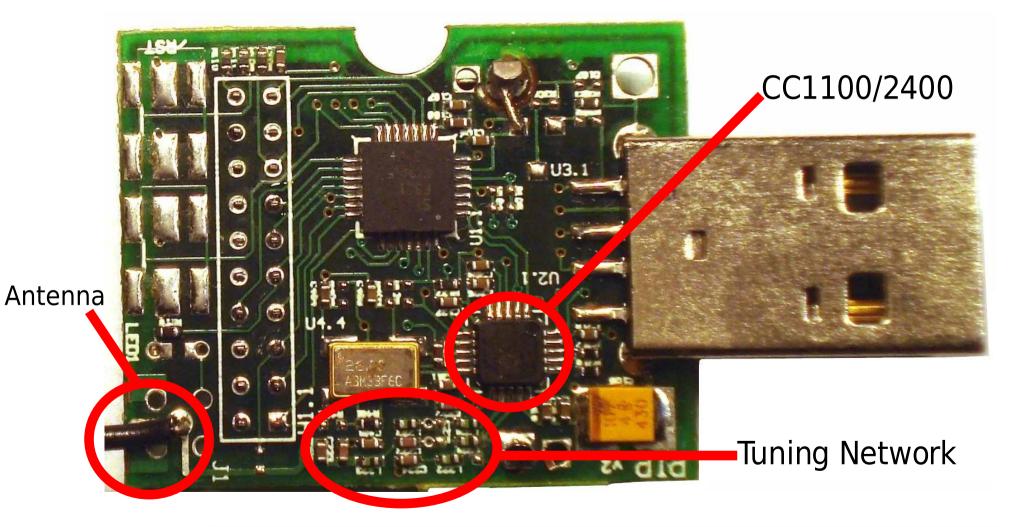






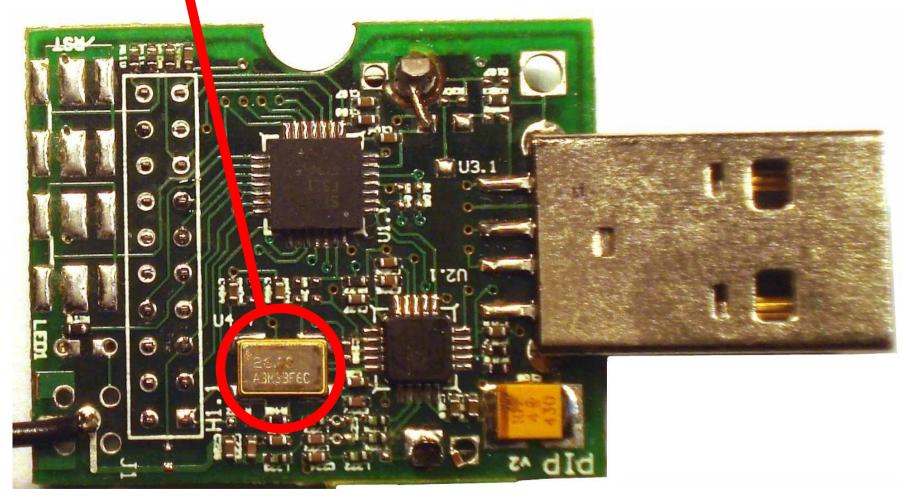




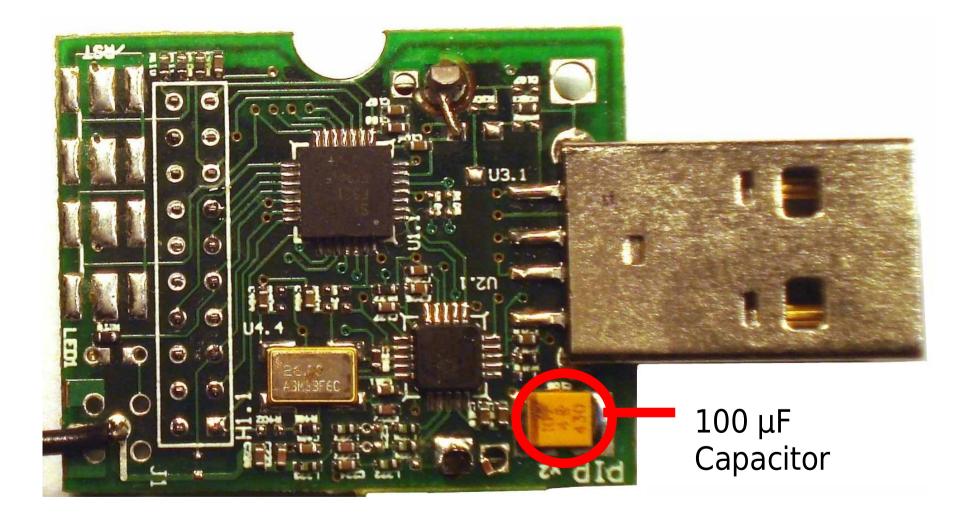




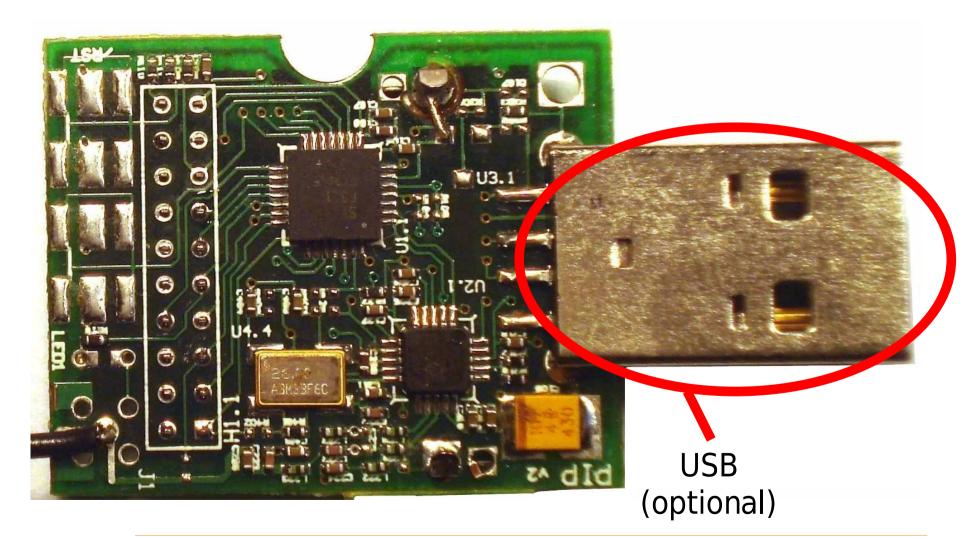
#### 26MHz Oscillator (MCU clock)













### **Comparison to Berkeley Motes**

#### PIPs

- Coin cell battery
  - Can be run with AA batteries using a special device.
- CC1100/2400 radio
- Programmed in C, use Keil μVision to flash.

### **Berkeley Motes**

- Many models
- AA batteries
- CC1100/2400 radio
- Programmed with TinyOS and NesC



### **PIP Software**

- Streamcollect
  - Our data collecting code. This receives data from multiple PIPs attached to a computer via USB.
     Data is stored in a sqlite3 database and can be printed to stdout.
- Analyze2
  - Analysis code that gives many statistics about a data set collected with Streamcollect.
- PIP codebase



## The existing codebase is useful

- SendBeacon
  - Sleep/Transmit/Sleep cycle with optional frequency hopping
- Listen4Beacons
  - Receives packets and prints them via USB.
- Jamming code
  - Continuous transmission of random bits
- Code for ACK and CS protocols also exists



# Rolling your own is easy

- Many parameters can be selected by changing a register or calling a function
  - Modulation format, Rx/Tx frequency, transmission power, FEC, Data Whitening, transmission duty cycle, etc
- It is easiest to start with existing code and change it to suite your needs



## How PIP programming works

- All of the default register values for the CC1100 are set in RegSettings\_X.c
- Change default register values or call halSpiWriteReg to set register values.
- Look at the CC1100/2400 data sheets to see what registers do:
  - focus.ti.com/lit/ds/symlink/cc1100.pdf
  - focus.ti.com/lit/ds/symlink/cc2400.pdf



## Changing the frequency

- #include <Rollcall\tuning.h>
- •
- setFreq(902100000.0)



## Writing data to the USB FIFO

- #include "queue.h"
- #include "F32x\_USB\_Structs.h"
- #include "usb\_init.h"
- ....
- //Initialize global USB queue
- host\_queue\_p = queue\_init();

```
•
```

queue\_insert(host\_queue\_p, str, sizeof(str));



## Sending variable length packets

- #include <Rollcall\rfsuite.h>
- ....
- //Data whitened, variable packet length
- halSpiWriteReg(CCxxx0\_PKTCTRL0, 0x41);
- BYTE packet[] = {length, ....};
- rfSendPacketNonblock(packet, sizeof(packet));



## Receiving variable length packets

- #include <Rollcall\rfsuite.h>
- ....
- //Data whitened, variable packet length
- halSpiWriteReg(CCxxx0\_PKTCTRL0, 0x41);
- BYTE rx\_buffer[psize];
- BYTE status[2];
- UINT8 len;
- rfReceive(rx\_buffer, &len, status);



## Transmitting random data

- #include <Rollcall\rfsuite.h>
- ....
- //Infinite length transmission with random data
- halSpiWriteReg(CCxxx0\_PKTCTRL0, 0x22);
- halSpiStrobe(CCxxx0\_STX);
- //Infinite loop so the packet never ends
- while(1);



## Keep the PIP in mind

- The PIPs are perfect to doing quick tests
- A few measurements can verify your assumptions before you do a large simulation or test
- PIPs are also a great tool to use when trying to gain experience using are measurement tools

