

Distributed Measurements for Estimating and Updating Cellular System Performance

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Abstract—We investigate the use of distributed measurements for estimating and updating the performance of a cellular system. Specifically, we discuss the number and placement of sensors in a given cell for estimating its signal coverage. Here, an “outage” is said to occur at a location if a mobile receiver there has inadequate signal-to-noise ratio (*SNR*-based outage) or, using another criterion, inadequate signal-to-interference ratio (*SIR*-based outage); and the “outage probability” is the fraction of the cell area over which outage occurs. A design goal is to improve measurement efficiency (i.e., minimizing the required number of measurement sensors) while accurately estimating the outage probability and mapping the coverage holes. The investigation uses a generic path loss model incorporating distance effects and spatially correlated shadow fading. Our emphasis is on the performance prediction accuracy of the sensor network, rather than on cellular system analysis *per se*. Through analysis and simulation, we assess several approaches to estimating the outage probability. Applying the principle of importance sampling to the sensor placement, we show that a cell outage probability of P_o can be accurately estimated using $\sim 10/P_o$ power-measuring sensors distributed in a random uniform way over the area with base-sensor distances from 50% to 100% of the cell radius. This result applies to both *SNR*-based and *SIR*-based outage estimation for both indoor and outdoor environments.

Index Terms—Distributed measurements, cellular systems, importance sampling, sensor networks, path loss.

I. INTRODUCTION

WE investigate the use of distributed measurements in a cell via sensors at known locations. The aim is to assist radio resource management in maximizing the quality of service in cellular systems. Our focus is on new or envisioned cellular system designs in which antenna beams, power per beam and channel sets can be assigned adaptively to accommodate slowly changing conditions of the propagation and the user population. The sensor-measured data can reduce the measurement demands on the active mobiles; or, it can be augmented by such measurements, to permit more dynamic adapting as individual mobiles change locations, start and end service, and so on.

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The key benefit of the distributed measurement system is that it provides round-the-clock measurements from many low-cost sensors per cell, at known locations. The data so obtained can be used not only for medium-term radio resource management, but also for longer-term engineering, e.g., identifying the need for new cell sites. RF planning for wireless systems utilizes both proactive measurements (e.g., path loss) and reactive measurements (e.g., call drops, handovers). For proactive measurements, in most cases, currently used RF planning tools gather propagation information based on the use of a database in a given region, augmented by drive tests conducted during off-peak times. Such static snapshots of RF planning information are suitable for current systems with fixed antenna patterns and limited use of adaptive algorithms. Data collected by mobiles and relayed to base stations may deliver additional time-of-day-specific RF planning information. However, relying on mobiles alone to provide signal and interference power measurements has limited benefit and adds demands to scarce mobile battery resources. Furthermore, a given mobile can measure downlink conditions only, may not be equipped with GPS receivers to help associate its measurements with location, and reports at uncontrolled times and locations.

Distributed measurements can react to gradual changes in propagation (e.g., new structures, especially in cities) or interference (e.g., due to adaptive beamforming). They are not labor-intensive and are available at all times, to accommodate slow adaptive changes in radio resources. The sensors can be more numerous and measurements may be gathered more-or-less uniformly from known locations, facilitating reliable outage evaluations. In fact, the potential exists to accurately pinpoint chronically poor service areas that arise after initial planning, and to identify the need for new or reengineered sites. Additionally, the sensor network could be extended to support multiple air interfaces within overlapping coverage regions (e.g., wireless LAN, DVB-H deployments).

We envision a network fabric of N sensors per cell ($N \sim 100$) which communicate with each other and, through some sensors, with the cellular system, as shown in Fig. 1. Each sensor has an identifying code and a fixed and known location, and it measures received powers from pilots sent by its closest base and several bases nearby. As we will show, the collection of data from all the sensors can be used to estimate the percentages of each cell having adequate signal-to-noise ratio (*SNR*), or adequate signal-to-interference ratio (*SIR*). The percentage of the cell that is *not* having sufficient *SNR* (or *SIR*) is called the *outage probability*, P_o .

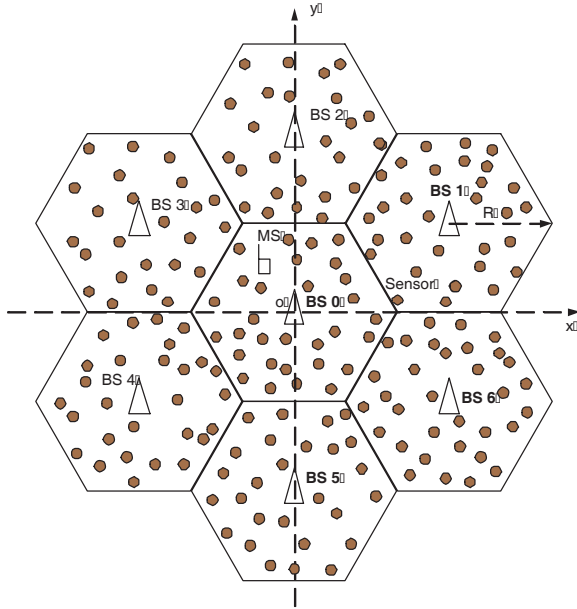


Fig. 1. A 7-cell cluster, with many sensors in each cell. We evaluate “outage” conditions in the center cell, both *actual* and as estimated using the sensors.

Our calculations are based on a path loss model that incorporates the effects of path length (distance) and spatially correlated shadow fading, as discussed in Section II. We then apply the principle of *importance sampling* (IS) in the placement of sensors and discuss how it might decrease the number of sensors required for a given accuracy in estimating P_o (Section III). Here, we derive an optimal sensor placement strategy for SNR-based estimation of P_o and also introduce three sub-optimal (but more generic) placement schemes. Next, we describe the use of Monte Carlo simulations to quantify the accuracy in estimating P_o as a function of the number of sensors (N), the placement scheme, and various system and path loss model parameters (Section IV). The results, for both SNR-based and SIR-based estimation, reveal the values of N needed for good accuracy and show the possible reductions in N using IS-type sensor placement. We also briefly discuss the use of the distributed measurements to generate outage (or *hole*) maps. We conclude (Section V) with a general discussion of distributed measurements to assist cell engineering, and we summarize our main findings.

II. SYSTEM MODEL

We assume each of N sensors in a given cell with radius R measures the received power of a downlink pilot signal. We also assume that the pilot power measurement is over a bandwidth sufficiently wide (5 MHz or more) that multipath fading is essentially averaged out. Thus, the measurement of received power P_R , combined with knowledge of the downlink transmit power per user and the antenna gains, permits the network to estimate the downlink path loss, PL . For our purposes, it is fair to assume that the antenna gains are independent of sensor position, so that the variation of P_R over the sensors precisely tracks the variation of PL , i.e., $P_R = C - PL$, where C is the same for all sensors. We note that, due to the averaging over multipath fading, this estimate applies to the uplink path loss as well.

Assuming the model of [1], the path loss (PL) from a base station (BS) to a location of the i -th sensor in the environment is

$$PL_i[\text{dB}] = A + 10\gamma \log(d_i/d_o) + s_i, \quad d_i > d_o, i = 1, \dots, N \quad (1)$$

where d_i is the distance from the BS to the i -th sensor and d_o is a reference distance (typically, 1 m indoors and 100 m outdoors). The intercept A is given by $20 \log(4\pi d_o/\lambda)$, where λ is the wavelength. The path loss exponent γ can range from 3 to 6, depending on the environment; the dB shadow fading, s_i , is a Gaussian process over space with zero mean and standard deviation σ ; and σ can range from 4 dB to 12 dB, depending on the environment. We assume that the autocorrelation of the spatial process s_i depends only on the separation distance, i.e.,

$$E[s_i s_j] = \sigma^2 e^{-d_{ij}/X_c}, \quad i, j = 1, \dots, N \quad (2)$$

where d_{ij} is the distance between the i -th and j -th sensors; and X_c , the shadow fading correlation distance, can range from several to many tens of meters [2]. We will assume a frequency of 2 GHz and $\gamma = 3.8$ in all our computations¹; and will consider different combinations of σ , X_c , d_o and cell radius for different cellular environments. We can thus use (1) and (2) to simulate the cell-wide variation of path loss.

For SNR-based estimation of outage probability, we compare the path loss, PL_i , to a threshold value PL_0 . That threshold is the value at which a mobile receiver near the sensor would have just enough fade-averaged signal-to-noise ratio for good reception². A hole in coverage (i.e., an outage) is defined as a location whose path loss from the BS is greater than the threshold, i.e., a hole exists at a location if $PL > PL_0$. The fraction of sensors measuring power below the threshold is the sensor network’s estimate of the cell’s SNR-based outage probability. The SNR-based approach is the same for the downlink and uplink. However the value of PL_0 may differ for the two directions, due to differences in transmit power, receiver noise level or air interface.

Figure 2 presents an outage map for a circular cell, where the dark spots indicate outages. The outage probability here is $P_o = 11.8\%$. Also, $N = 4000$ and $PL_0 = 120$ dB. The dark outage spots are seen to be concentrated in the outer regions of the cell. Placing sensors close to the center, therefore, can amount to wasting limited resources on what are predictably “non-events”. This brings us to the subject of importance sampling [7].

III. IMPORTANCE SAMPLING (IS) FOR OUTAGE PROBABILITY ESTIMATION

A. IS Concept and Analysis

Assume N sensors are placed in the circular cell with radius R , and the i -th sensor is at a distance d_i from the base at an azimuth angle φ_i , $i = 1, \dots, N$. Assume further

¹While γ can have a wide range of values [1], the most common cellular values cited on the literature range from 3.5 [3] to 4.0 [4]; hence, we choose 3.8 for our calculations.

²The multipath-averaged SNR is a valid determinant of link performance (e.g., see [5] and [6]), which is why our method is based on fade-averaged measurements.

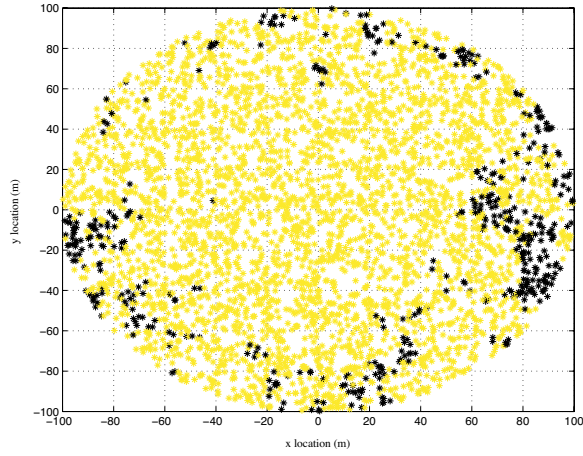


Fig. 2. An “outage” map for a single cell with 4000 uniformly located sensors. In this example, the cell radius is 100 m, $\sigma = 8$ dB, $X_c = 8$ m, and “outage” corresponds to the condition $PL > PL_o = 120$ dB. The dark dots indicate outages, which occur for 11.8% of all sensors, primarily in sensors located towards the cell boundary.

that each squared distance, $D_i = d_i^2$, is drawn from a set of possible values on $[0, R^2]$ whose underlying probability density function (PDF) is $f(D)$; that each φ_i has a uniform PDF on $[0, 2\pi]$; and that all the D_i and φ_i are mutually independent. Thus, in populating a given cell with sensors, each sensor can be said to be placed independently and randomly according to the underlying PDF $f(D)$.

In a traditional Monte Carlo simulation, the sensors would be distributed randomly and uniformly over the full cell; we call this *full-cell* (FC) placement. Here, $f(D) = 1/R^2$ for $0 < D < R^2$, and zero otherwise. The estimated outage probability is an average over measurements by N sensors, given by

$$\hat{p}_{FC} = \frac{1}{N} \sum_{i=1}^N \phi(\xi_i) \quad (3)$$

where $\phi(\cdot)$ is an indicator function, i.e., $\phi(\xi_i) = 1$ if $PL_i > PL_o$, otherwise, $\phi(\xi_i) = 0$.

Now we consider what happens if we “bias” the placement of the sensors to the area where the outage is more likely to happen. Denote the PDF of D and d in the new placement as $f^*(D)$ and $f_d^*(d)$, respectively. By definition, we have $\int_0^{R^2} f^*(D) dD = 1$ and $f^*(D) \geq 0$. The estimated outage probability is

$$\hat{p}_{IS} = \frac{1}{N} \sum_{i=1}^N \phi(\xi'_i) W(\xi'_i) \quad (4)$$

where ξ'_i , $i = 1, \dots, N$ is the location of the i -th sensor, generated according to $f^*(D)$. The weight function $W(\cdot)$ seeks to “undo” the bias due to sampling with the biased placement.

The estimate of outage probability must be unbiased, i.e., $E[\hat{p}_{IS}] = E[\hat{p}_{FC}]$. Also, the variance should be smaller, i.e., $Var[\hat{p}_{IS}] < Var[\hat{p}_{FC}]$, which means that its estimate is *sharper* than that for full-cell placement with the same amount of sensors, or equivalently, requires fewer sensors for the same estimate sharpness. The average and the variance are taken over different random selections of the sensor positions

and the shadow fading realizations. This is the essence of *importance sampling* [7].

We now consider how to satisfy two conditions: (1) unbiased estimates of P_o , and (2) minimal estimator variance. To gain insight with minimal complexity, we assume $X_c = 0$ in the current analysis, i.e., the dB shadow fading are i.i.d Gaussian variables $N(0, \sigma^2)$. In our later computations, we will take shadow fading correlations into account.

Following (1), we write the average outage probability of FC placement over all realizations of the shadow fading as

$$\begin{aligned} \hat{P}_{FC} &= \frac{1}{N} \sum_{i=1}^N Pr(A + 10\gamma \log(d_i/d_o) + s_i > PL_o) \\ &= \frac{1}{N} \sum_{i=1}^N Q\left(\frac{PL_o - A - 10\gamma \log(d_i/d_o)}{\sigma}\right) \\ &= \frac{1}{N} \sum_{i=1}^N Q\left(\frac{\beta - \alpha \log(D_i)}{\sigma}\right) \end{aligned} \quad (5)$$

where $\alpha = 5\gamma$, $\beta = PL_o - A + 10\gamma \log(d_o)$.

Similarly, we write the average outage probability of IS placement as

$$\hat{P}_{IS} = \frac{1}{N} \sum_{i=1}^N Q\left(\frac{\beta - \alpha \log(D_i^*)}{\sigma}\right) W(D_i^*) \quad (6)$$

Condition 1 above amounts to $(E[\hat{P}_{FC}] = E[\hat{P}_{IS}] = P_o)$, so we require that

$$W(D) = \frac{f(D)}{f^*(D)} = \begin{cases} \frac{1/R^2}{f^*(D)}, & 0 < D < R^2 \\ 0, & \text{otherwise} \end{cases} \quad (7)$$

which indicates that $f^*(D) > 0$ throughout $0 < D < R^2$.

Condition 2 amounts to minimizing $Var[\hat{P}] = E[\hat{P}^2] - E^2[\hat{P}]$, i.e.,

$$\begin{aligned} Var_{f^*(D)}[\hat{P}] &= E_{f^*(D)}[\hat{P}^2] - P_o^2 \\ &= \frac{1}{N^2} E\left[\sum_{i=1}^N \sum_{j=1}^N Q\left(\frac{\beta - \alpha \log(D_i^*)}{\sigma}\right) W(D_i^*) \right. \\ &\quad \left. Q\left(\frac{\beta - \alpha \log(D_j^*)}{\sigma}\right) W(D_j^*)\right] - P_o^2 \\ &= \frac{1}{N} E_{f^*(D^*)} \left[\left(Q\left(\frac{\beta - \alpha \log(D^*)}{\sigma}\right) W(D^*) \right)^2 \right] - \frac{P_o^2}{N} \\ &= \frac{1}{NR^4} \int_0^{R^2} \frac{Q^2\left(\frac{\beta - \alpha \log(D)}{\sigma}\right)}{f^*(D)} dD - \frac{P_o^2}{N} \end{aligned} \quad (8)$$

where the third line follows from the independence of $W(D_i^*)$ and $W(D_j^*)$, $i \neq j$, and

$$\begin{aligned} P_o &= E_{f(D)}[\hat{P}_{FC}] = E_{f^*(D)}[\hat{P}_{IS}] = E\left[Q\left(\frac{\beta - \alpha \log(D)}{\sigma}\right)\right] \\ &= \int_0^{R^2} Q\left(\frac{\beta - \alpha \log(D)}{\sigma}\right) dD/R^2 \end{aligned} \quad (9)$$

B. Optimal Sensor Placement Scheme

From the above discussion, we can see that $f^*(D)$ for the optimal sensor placement is given by

$$\begin{aligned} \min \quad & Var_{f^*(D)}[\hat{P}] \\ \text{s.t.} \quad & \int_0^{R^2} f^*(D) dD = 1 \end{aligned} \quad (10)$$

where $f^*(D) > 0$ for $0 < D < R^2$. Its Lagrangian form is

$$L(f^*, \lambda) = \int_0^{R^2} \left(Q^2 \left(\frac{\beta - \alpha \log(D)}{\sigma} \right) / f^*(D) + \lambda f^*(D) \right) dD \quad (11)$$

Then the optimization reduces to minimizing $L_2(f^*, \lambda) = Q^2 \left(\frac{\beta - \alpha \log(D)}{\sigma} \right) / f^*(D) + \lambda f^*(D)$, subject to the constraint in (10). This leads to the following solution for the PDF of D :

$$f^*(D) = \begin{cases} Q \left(\frac{\beta - \alpha \log(D)}{\sigma} \right) / \eta, & 0 < D < R^2 \\ 0, & \text{otherwise} \end{cases} \quad (12)$$

where $\eta = \int_0^{R^2} Q \left(\frac{\beta - \alpha \log(D)}{\sigma} \right) dD$. The corresponding optimal PDF for d is

$$f_d^*(x) = \begin{cases} 2xQ \left(\frac{\beta - 2\alpha \log(x)}{\sigma} \right) / \eta, & 0 < d < R \\ 0, & \text{otherwise} \end{cases} \quad (13)$$

This is a parametric scheme in that it requires knowledge of channel parameters, such as σ and $\gamma (= 0.2\alpha)$. Further, this optimal placement essentially requires knowledge of the outage probability P_o , as can be seen from (9) and the above definition of η . In traditional IS methods, such an optimal solution is referred to as degenerate, since it requires knowledge of the true value of the quantity being estimated.

C. Semi-Parametric Placement Schemes

Motivated by the importance sampling idea above and to overcome the degenerate problem, we propose three sensor placement schemes that are *semi-parametric*, that is, each exploits the knowledge that power generally falls off with distance but does not attempt to know or exploit the precise nature of that falloff. Each scheme is defined by the PDF it uses for the base-to-sensor distance, d ; the *angular* PDF in each case is uniform on $[0, 2\pi]$, as before. The three distance PDFs we consider are the following:

$$\text{Scheme 1: } f_d(x) = \begin{cases} 4x^3/R^4, & 0 < x < R \\ 0, & \text{otherwise} \end{cases} \quad (14)$$

$$\text{Scheme 2: } f_d(x) = \begin{cases} 6x^5/R^6, & 0 < x < R \\ 0, & \text{otherwise} \end{cases} \quad (15)$$

$$\text{Scheme 3: } f_d(x) = \begin{cases} \frac{2x}{R^2 - R_{min}^2}, & R_{min} < x < R \\ 0, & \text{otherwise} \end{cases} \quad (16)$$

Unlike the first two schemes, Scheme 3 is based on the assumption that there are no holes in the inner area of the cell, i.e., at locations with distances smaller than R_{min} . Here, all the sensors are distributed uniformly in the outer ring of the cell, i.e., at locations with distances between R_{min} and R . Accordingly, we call Scheme 3 *partial-cell* (PC) placement. From Fig. 3, we see that these PDFs, and especially the one for Scheme 2, are good approximations to the PDF that was shown to be optimal for the case $\gamma = 3.8$, $\sigma = 8$ dB, $X_c = 0$ and $P_o = 0.05$. How this translates into performance is a topic we address next.

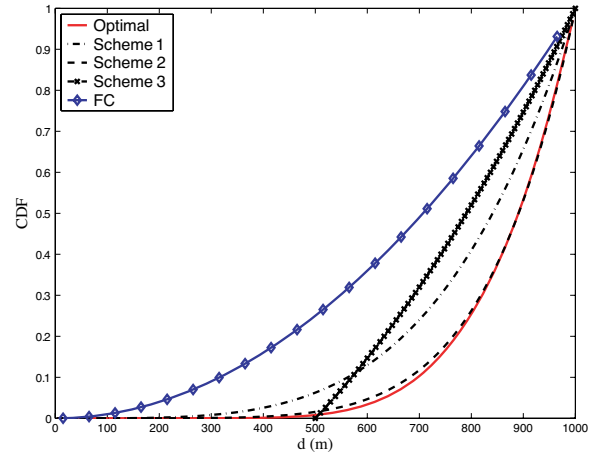


Fig. 3. CDF of d for five sensor placement schemes, including full-cell (FC) placement. The “optimal” scheme is for the case $\gamma = 3.8$, $\sigma = 8$ dB, $X_c = 0$, $R = 1000$ m, and $P_o = 0.05$. Scheme 3 is partial-cell (PC) placement with $R_{min} = 0.5R$.

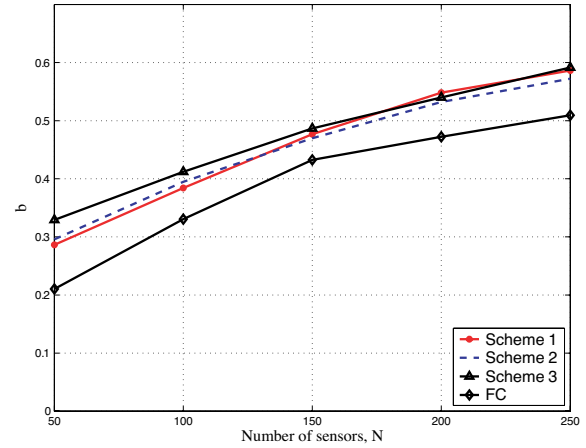


Fig. 4. b vs. N , where $b = Pr[|\hat{P}_o - P_o| < 0.2P_o]$, with $R = 1000$ m, $\gamma = 3.8$, $\sigma = 8$ dB, $X_c = 50$ m, and $P_o = 0.05$.

IV. SIMULATION RESULTS ON OUTAGE PROBABILITY ESTIMATION

A. Preliminary Result

Figure 4 presents the probability that the error in estimating P_o falls within $\pm 20\%$ of the true value, which is 0.05 in this example. Similar results were obtained for $P_o = 0.10$. It is seen that the three IS-based schemes cited above have similar performance, and all of them are better than full-cell placement. Among the IS-based schemes, Scheme 3 (partial-cell placement, (16)) is easy to implement and has very good performance. In the remainder of the paper, we will compare it with full-cell placement for both *SNR*-based and *SIR*-based outages and for both indoor and outdoor environments.

B. Simulation Approach

In our simulations, we initially assume a circular cell of radius R (later, we discuss circular vs. hexagonal cell shapes), and we assign values to R and the propagation parameters in (1) and (2). We simulate some number, N_{sh} , of statistically similar cells, with each having a different spatial variation of s , the dB shadow fading. We start by simulating $s(\xi)$ for Cell 1,

where ξ denotes position within the cell. This random spatial variation is simulated using (2) and Cholesky decomposition, as described in [8]. The next step is to choose a value for N , the number of sensors per cell; a placement for the N sensors; and a path loss threshold, PL_o , the determination of which is described below. Finally, the path loss at each of the sensors is computed, and the outage probability in Cell 1, $p_o(1)$, is determined as the fraction of sensors for which $PL > PL_o$.

With $s(\xi)$ fixed, the N -sensor placement is chosen a total of M times and, if M is sufficiently large, the mean and standard deviation of $p_o(1)$, μ_1 and σ_1 , respectively, can be estimated. (Note that these are the mean and standard deviation taken over the random placements of the N sensors within the cell.) This procedure is repeated for a total of N_{sh} generations of the shadow fading variation $s(\xi)$, corresponding to Cells 1, \dots , N_{sh} . The average of μ_j over j is the network's estimate, denoted by P_o^* , of the true outage probability; and the average of σ_j over j , denoted by ρ , is the network's estimate of the intra-cell standard deviation due to the random N -sensor placement. We call ρ the "sharpness" of the estimate, and seek to make it as small as $0.25P_o$ or less.

The baseline value of P_o , i.e., what we assume to be the true one, is obtained by first assigning an extremely large value for N . We have found, by a combination of analysis and simulation not shown here, that $N = 4000$ would yield precise estimates in any cell, with negligible variation from one placement of N sensors to another. For that N , we (1) computed outage probability for each of N_{sh} realizations of $s(\xi)$, for each of several values of path loss threshold, PL_o ; (2) averaged over the N_{sh} values for each PL_o ; and (3) took the result to be the "true" outage probability, P_o , for that path loss threshold. We were thus able to identify the values of PL_o producing average outage probabilities of 0.05 and 0.10. We applied the procedure described in the previous paragraph for each of these P_o -values, using practical values of N (namely, 50, 100, 200, 300, and 400). For each of these N , we did $M = 200$ placements for each of $N_{sh} = 10$ realizations of the shadow fading variation, $s(\xi)$.

C. SNR-Based Outage Probability

First, we investigate an outdoor system with the usual hexagonal cells, in particular, a center cell and six surrounding cells (Fig. 1). The center cell, for which we will analyze outage probability estimation, is conveniently assumed to be circular, with a radius, R , chosen such that the circle has the same area as the actual hexagonal cell. This will simplify analysis with no loss in accuracy; other studies (e.g., [9]) have shown cell shape to be a negligible factor so long as cell area is preserved³. The shadow fading parameters (σ, X_c) are initially set at (8 dB, 50 m). We set PL_o at values that yield "true" outage probabilities, P_o , of 0.05 and 0.10. For each of these two values, we have computed the corresponding estimate, P_o^* , for both full-cell sensor placement ($R_{min} = 0$) and partial-cell placement ($R_{min} = 0.5R$ and $0.7R$).

Simulation results for P_o^* are shown in Table I. The estimates obtained are independent of N except for a slight

³We note further that the regular hexagon closely approximates a circle, which is why early investigators chose it as the tessellating shape to use in cellular studies [10], [11].

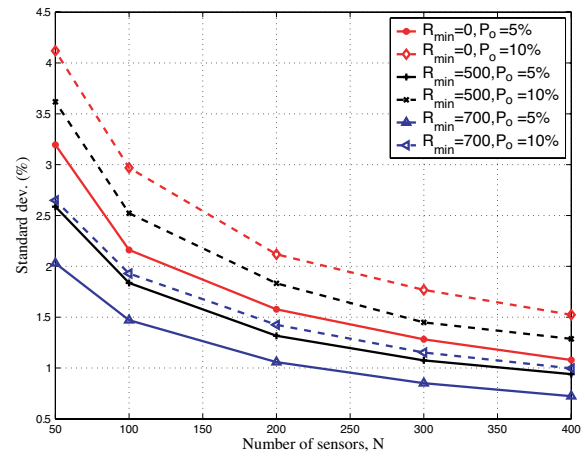


Fig. 5. Standard deviation of estimate for $P_o = 0.05$ and 0.10 , $R = 1000$ m, and $(X_c, \sigma) = (50 \text{ m}, 8 \text{ dB})$.

fluctuation due to finite simulation, so the numbers shown are averages of those obtained for several values of N . We see that the estimation of P_o is virtually unbiased for R_{min} up to at least $0.5R$, i.e., there are virtually no outages to be counted at smaller distances. At $R_{min} = 0.7R$, however, the estimation is biased downward because outages can occur at base-terminal distances between $0.5R$ and $0.7R$ and are not counted.

For the same case, we obtained simulation results for ρ , the average standard deviation of the estimate resulting from the random placement of N sensors. Here, we expect to see a decrease with N , as is confirmed by the plots in Fig. 5. The "sharpness" of the estimates improves not only with increasing N , but also with increasing R_{min} , because larger R_{min} leads to a higher density of sensors in the area containing them. A near-best tradeoff between small bias error and maximum "sharpness" occurs for $R_{min} = 0.5R$, at least for the assumed model. For ρ to be no greater than $0.25P_o$, the figure shows that the required N for $P_o = 0.05$ is ~ 200 for $R_{min} = 0.5R$ and ~ 300 for $R_{min} = 0$ (full placement). For $P_o = 0.10$, the required N -values are ~ 100 and 150 , respectively. Thus, a simplified form of importance sampling reduces the required number of sensors by about 33%. The general rule is that, with $R_{min} = 0.5R$, the required N is $\sim 10/P_o$, which is consistent with binomial statistics.

Next, we assume an indoor environment with $R = 100$ m, and we consider three different sets of shadow fading parameters (σ, X_c): (8 dB, 8 m), (8 dB, 50 m) and (10 dB, 50 m). Results are given in Table I and Fig. 6 for $P_o = 0.10$. These results, and those for $P_o = 0.05$ as well (not shown), reinforce the findings from the previous example. Moreover, they show that the shadow fading parameters have some influence, but they do not change the general rules for R_{min}/R and N .

D. SIR-Based Outage Probability

While the above study of SNR-based outage probability was generic, the study of SIR-based outage probability requires specificity about the radio interface. For this purpose, we assume a CDMA system with a spreading factor of 128 and

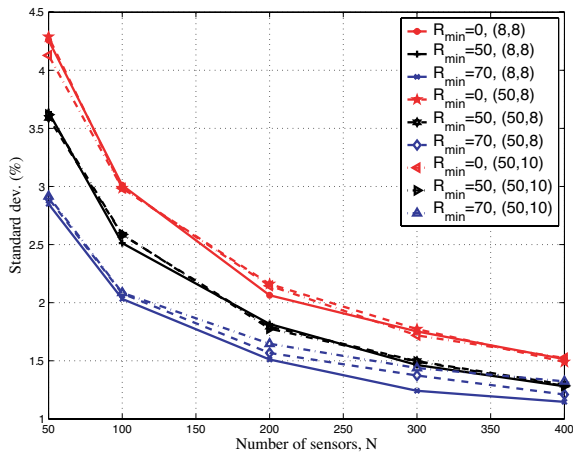


Fig. 6. Standard deviation of estimate for $P_o = 0.10$, $R = 100$ m, and (X_c, σ) : (8 m, 8 dB), (50 m, 8 dB), (50 m, 10 dB).

a required receiver output SIR of 5 dB. For simplicity, we assume that the downlink co-channel interference from the six surrounding cells is dominant. Also, we assume that each sensor is able to identify, from downlink pilots, the power from each base (its own plus the six nearest interfering bases) [12]; that each base is transmitting its full rated power; and that an “outage” occurs for a mobile if its serving base runs out of power before it is able to meet that mobile’s SIR requirement. These assumptions, combined with the above path loss model, enable us to compute outage probability for a given number, K , of active mobiles per cell (or sector).

We note that for $K > 1$, there is one more layer of randomness, besides those for the shadow fading distribution and the sensor placement, namely, the placement of the K mobiles. Thus, for every combination of $s(\xi)$ -realization and N -sensor placement, the network computes an outage probability for each of M_{mt} random placements of K mobiles over the cell, then averages the M_{mt} values. In our study, we used $M_{mt} = 200$.

The above steps are straightforward for full-cell placement ($R_{min} = 0$). However, we also considered partial placement, specifically, $R_{min} = 0.5R$. In this case, the N sensors are uniformly distributed over $3/4$ of the cell area, but no sensors are in the inner region ($d < 0.5R_{min}$), where, on average, $1/4$ of the K mobiles would be located. This poses a question of how to compute outage probability. To address it, the network can estimate P_o as follows: (1) compute an upper bound by assuming *all* of the K mobiles are in the outer region; (2) compute a lower bound by assuming that $3/4$ of the K mobiles are in the outer region and *none* are in the inner region⁴; and (3) estimate P_o as the mean of the two bounds. Our computations show that the upper and lower bound differ from their mean by 3.3%, 5.0% and 6.5% for $K = 4, 8$ and 12 , respectively, so the bounds are clearly tight.

Some results are given in Table I and Fig. 7. In Table I, the increase in P_o with K , due to the dividing of transmit power among more mobiles, is evident but mild. In Fig. 7, we

⁴With $K/4$ mobiles in the inner region, as in an actual K -mobile scenario, P_o will be higher, due to greater interference; thus, the situation where those $K/4$ mobiles are absent yields a lower-bound P_o .

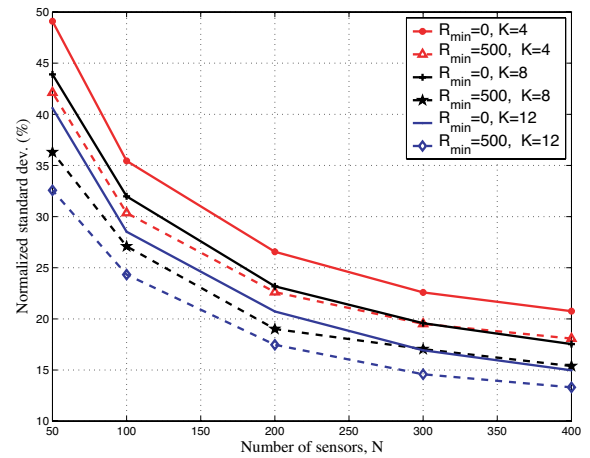


Fig. 7. Normalized standard deviation (ρ/P_o) with $R = 1000$ m, $\sigma = 8$ dB and $X_c = 50$ m.

see, as before, that partial placement with $R_{min} = 0.5R$ and $N \sim 10/P_o$ yields the desired level of “sharpness”.

Extensions of this case might take into account issues such as base station selection (e.g., SIR -based as opposed to distance-based, as assumed here), other kinds of interference (outer rings, intra-cell, etc), location information and uplink performance. Regarding the latter, we note that each sensor is assumed to be able to estimate its path loss (which is essentially the same in both directions) to the seven nearest bases. This information, plus some additional computing, would allow the sensor network to estimate *uplink* outage probabilities, as well. The availability of location information can be used to map the variations in outage regions, as we briefly discuss next.

E. Outage Maps

Here, we consider how to draw an “outage map” using data collected by the sensors. Specifically, given the quality of the links to N locations, we would like a map that shows or predicts most of the outage locations within a cell. One possibility is to center a circular area (“neighborhood”) with radius R_c about each sensor that detects an outage. The neighborhoods so identified can be considered to be outage regions requiring some sort of engineering attention.

Figure 8 illustrates one such example, where $N = 200$ sensors are used and $R_c = 100$ m in a cell of 1-km radius. All diamonds represent sensor locations; all stars represent outage locations (out of the 4000 locations from which the sensor locations are chosen); and each circle denotes an outage “neighborhood”, at the center of which is a sensor that detects and declares an outage. All stars outside of the circles denote outage locations that are not detected.

Figure 9 exemplifies the average percentage of outage locations detected as a function of R_c/R , using partial-cell placement with $R_{min} = 0.5R$. The averaging in these results is over both sensor placements and shadow fading realizations; and the outages are SNR-based. The parameters varied are the shadow fading correlation distance and the number of sensors. Other conditions assumed are given in the figure caption.

We see that the percentage of holes detected increases with N , X_c and R_c/R , though the rate of improvement falls with

TABLE I
ESTIMATED DOWNLINK OUTAGE PROBABILITY.

CASE	$R_{min} = 0$	$R_{min} = 0.5R$	$R_{min} = 0.7R$
<i>SNR-Based; Outdoor Cell ($R = 1000$ m); $(\sigma, X_c)=(8$ dB, 50 m)</i>			
“True” $P_o = 0.05$	0.050	0.050	0.044
“True” $P_o = 0.10$	0.100	0.098	0.086
<i>SNR-Based; Indoor Cell ($R = 100$ m); “True” $P_o = 0.10$</i>			
$(\sigma, X_c)=(8$ dB, 8 m)	0.100	0.099	0.089
$(\sigma, X_c)=(8$ dB, 50 m)	0.099	0.100	0.092
$(\sigma, X_c)=(10$ dB, 50 m)	0.100	0.099	0.089
<i>SIR-Based; Outdoor Cell ($R = 1000$ m); CDMA System; $(\sigma, X_c)=(8$ dB, 50 m)</i>			
$K = 4$ ($P_o = 0.076$)	0.075	0.074	-
$K = 8$ ($P_o = 0.088$)	0.088	0.087	-
$K = 12$ ($P_o = 0.103$)	0.103	0.100	-

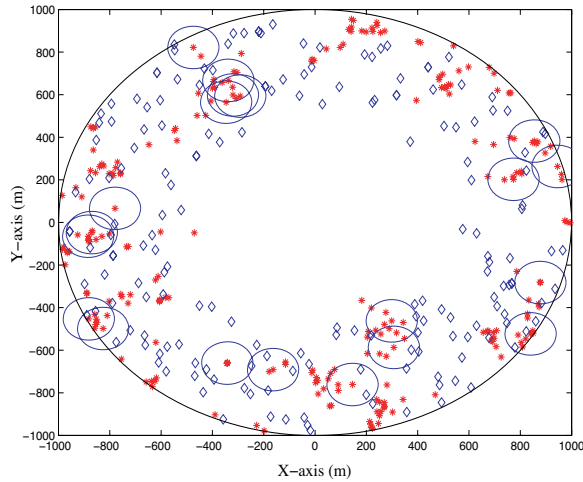


Fig. 8. An “outage map” for a single cell using data collected by $N = 200$ sensors. In this example, the cell radius $R = 1000$ m, $R_c = 100$ m, $\sigma = 8$ dB, $X_c = 50$ m. All diamonds represent sensor locations; all stars represent outage locations; and each circle denotes an outage “neighborhood”, at the center of which is a sensor that detects and declares an outage. All stars outside of the circles denote outage locations that are not detected.

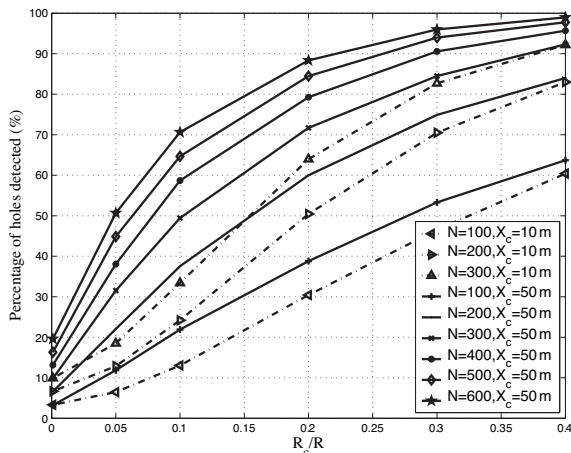


Fig. 9. Percentage of holes detected by N sensors in partial-cell placement, with $R_{min} = 0.5R$, $P_o = 0.05$, $\sigma = 8$ dB, $\gamma = 3.8$, $R = 1000$ m, and various combinations of N and X_c . R_c ranges from 1 m to 400 m.

N . Also note that the interesting region of values of R_c/R is the low end, typically 0.1 and below, where a “neighborhood” is no bigger than $\sim 1\%$ of the cell area. In this range, the difference between correlation distances of 10 m and 50 m can be substantial. Also, 200 sensors is not nearly enough

to capture, on average, the majority of the outages. For that purpose, at least 300 sensors are needed, and as many as 600 are needed to detect 70% of all outages. To detect that percentage using ~ 200 sensors, the sensor data would have to be augmented by other information, such as topographical maps, building location data, and so on.

V. DISCUSSION AND CONCLUSION

We applied the principle of importance sampling to improve the efficiency of the distributed measurements in cellular systems. Specifically, we investigated ways to minimize the number (N) of sensors needed to estimating the signal coverage of the cells. We derived, for a particular set of parameters, an optimal sensor placement scheme for estimating cell outage probability; and we used it to postulate schemes that require no specific parameter information. Among them, we emphasize a version of partial-cell placement, wherein the power-measuring sensors are distributed in a random uniform way over base-mobile distances from 50% to 100% of the cell radius. Its performance was compared with that of full-cell placement. It was shown that a cell outage probability of P_o can be accurately estimated using $\sim 10/P_o$ sensors with partial-cell placement; and that this represents a reduction, relative to full-cell placement, of $\sim 33\%$. This result applies to both *SNR*-based and *SIR*-based outage estimation for both indoor and outdoor environments. We also presented a way to draw outage maps based on measurement data from the sensors, and showed that many more sensors are required to capture most of a cell’s outage locations.

While we have focused in this paper on sensor-based information, a given operator may want to consider a wide range of approaches, including: (1) The traditional combining of site data with drive testing; (2) deploying a dedicated network of sensors; (3) renting service from an existing multi-purpose sensor network; (4) using a set of subscriber mobiles, equipped with GPS, to periodically measure and report power measurements; and so on. For those approaches based on sensor or mobile measurements, the rate of measurement-and-report (e.g., hourly, daily, etc) can be tailored to maintain acceptable levels of battery drain. Choosing among candidate approaches would require a cost/performance tradeoff analysis that is beyond the scope of this study; our main purpose here has been to demonstrate that accurate outage estimation based on distributed power measurements is possible and moreover, that the required number of such measurements can be substantially reduced via importance sampling.

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