

# Understanding Spectrum

Speaker: Predrag Spasojevic

Students: Haris Kremo, Goran Ivkovic and Shridatt Sugrim

Co-Advisors: Ivan Seskar, Larry Greenstein, and Melike Gursoy

WINLAB Industrial Advisory Board Meeting  
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# Topics

- ORBIT Propagation Characterization (Haris Kremo)
- Localization of Packet Based Radio Transmitters in Space, Time, and Frequency (Goran Ivkovic)
- Channel Occupancy Analysis in Packet-Based Wireless Networks (Shridatt Sugrim)
- Other topics (not covered):
  - Vehicular channel spectrum sensing (Dusan Borota)
  - White Space Sensing (Jonathan Shah)

# Propagation Characterization of the ORBIT Radio Testbed

Haris Kremo

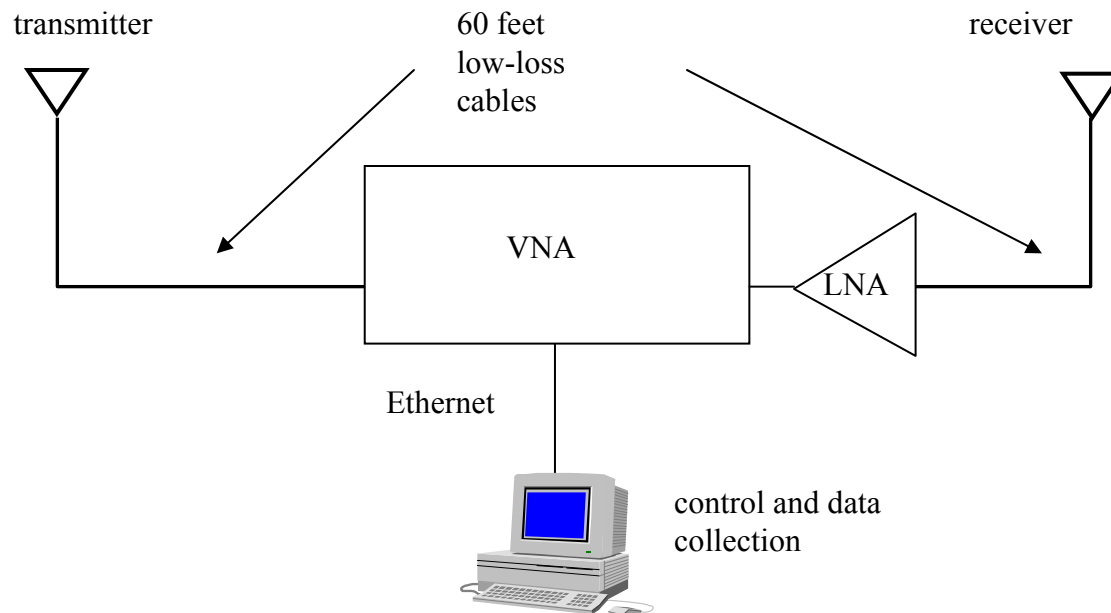
Ivan Šeškar, Larry Greenstein, and  
Predrag Spasojević

# Outline

- Motivation
- Measurements setup
  - vector network analyzer
- Measurements goals
  - determine path loss model
  - determine impulse responses (multipath intensity profile - MIP)
- MIP from two case studies compared to WISE simulations
  - 15 measurements diagonally across the room
  - 66 measurements for two symmetric transmitter positions
- Influence of antenna patterns on measurements
  - conclusions supported using WISE simulations

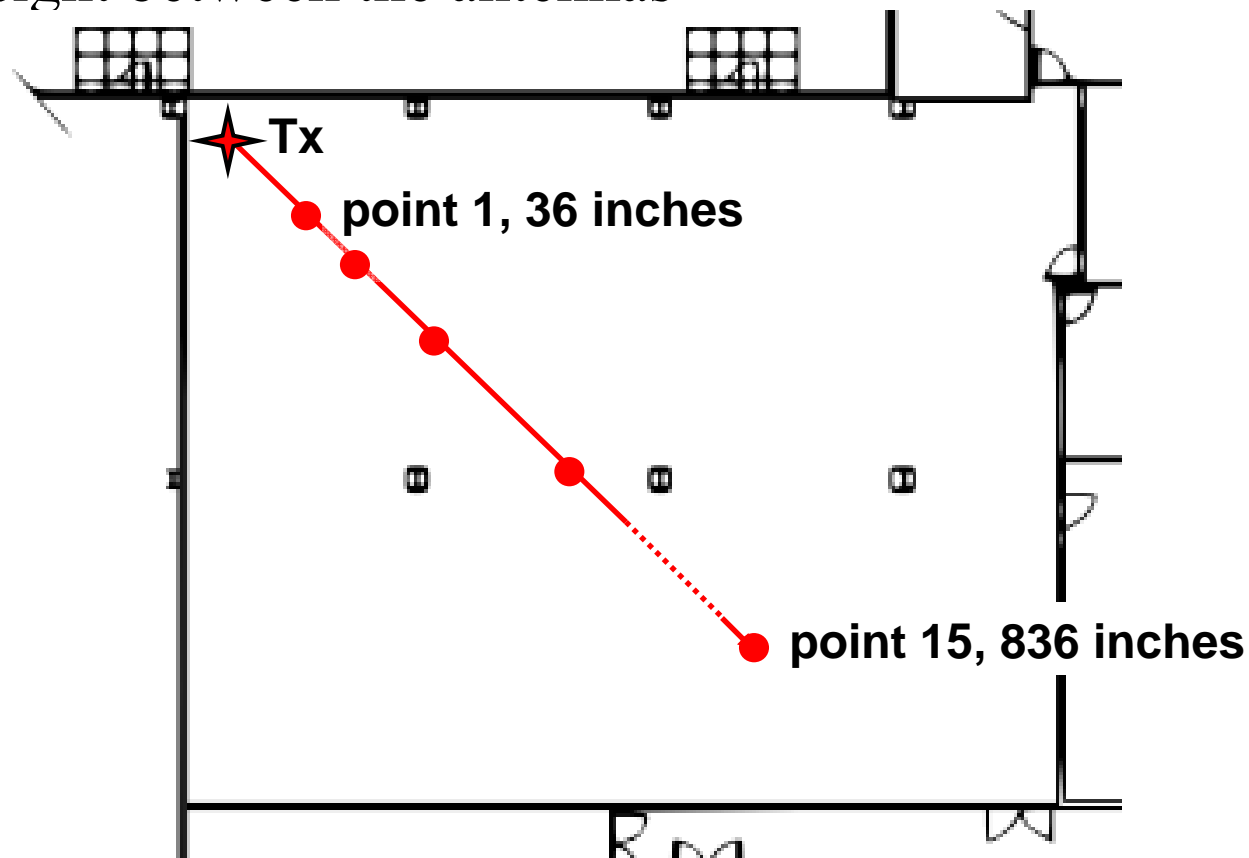
# Vector network analyzer (VNA): ORBIT Study

- Measure S-parameters
  - ISM/UNII 100 MHz bands

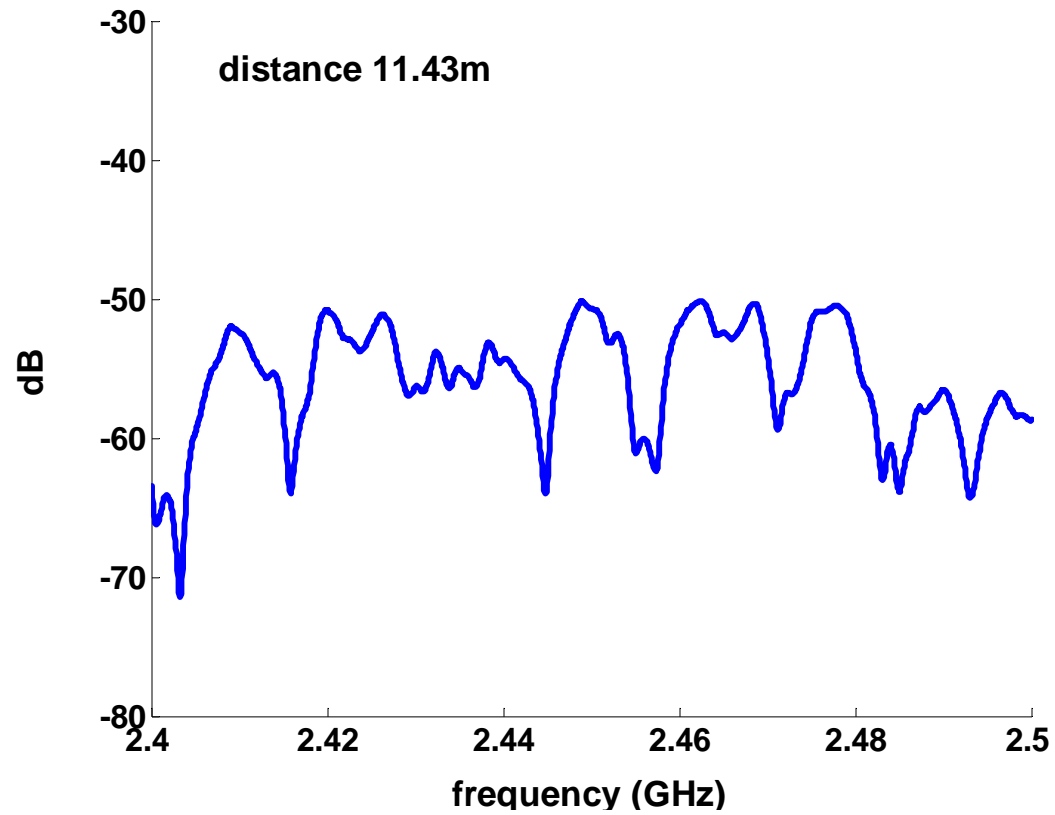


# Case study “receiver on a diagonal”

- Logarithmically distributed distances
- Line-of-sight between the antennas

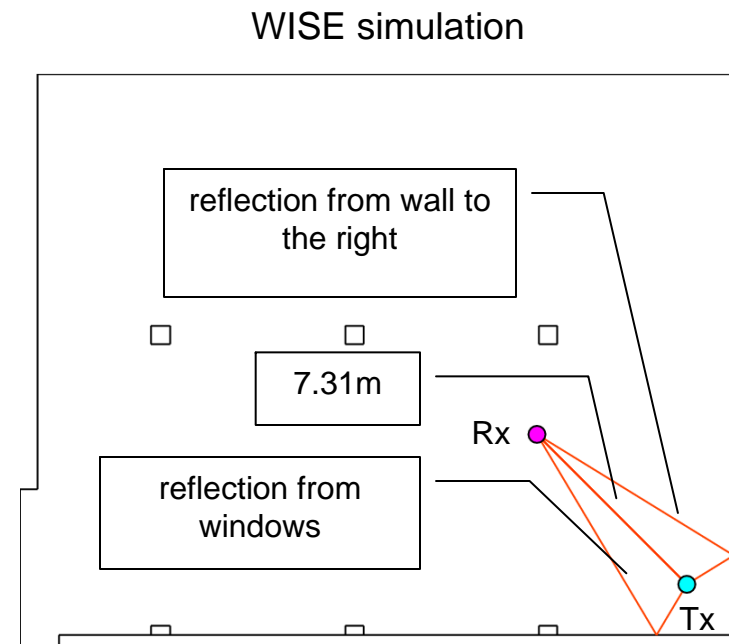
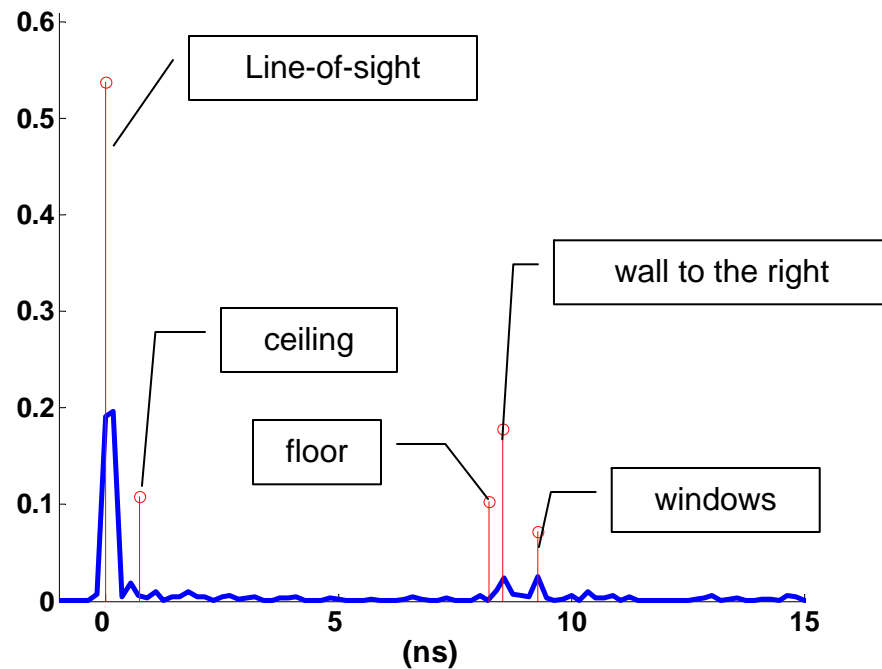


# Example channel response magnitude



# Example of Multipath Intensity Profile

- MIP compared to the results of WISE
  - Walls, windows significant source of reflections
  - Ceiling, roof, floor negligible source of reflections (due to antenna radiation pattern)





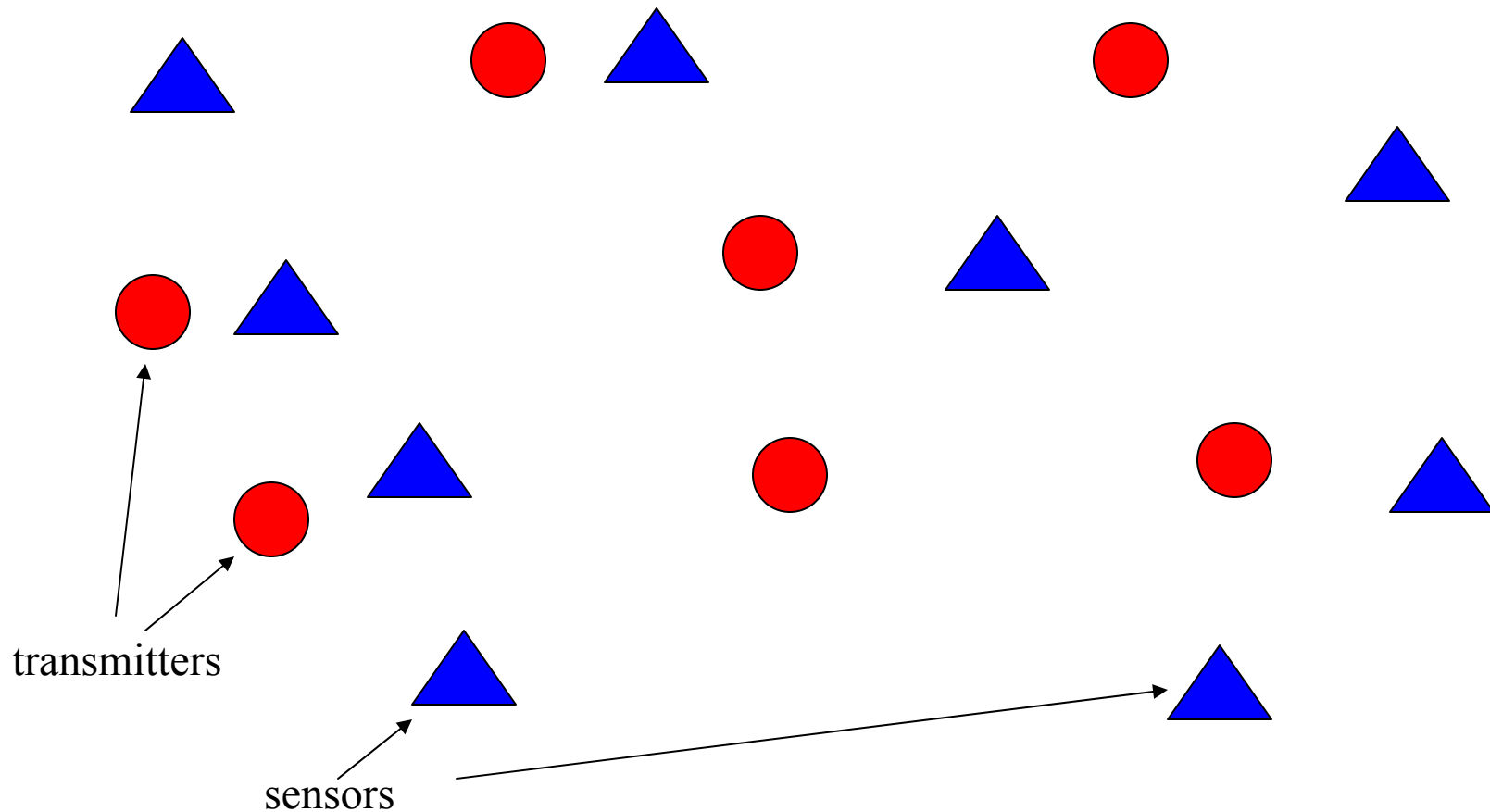
# Localization of Packet Based Radio Transmitters in Space, Time and Frequency

Goran Ivkovic

Advisors: Predrag Spasojevic and Ivan Seskar

# Spectrum Sensing Network

We consider the scenario where one or more sensors observe a frequency band possibly used by transmitters forming packet based radio networks



# Goal: Transmission Characterization

- Transmitters in these networks exchange packets using certain protocols
  - there are multiple transmitters producing signals with nonpersistent excitation
  - e. g., 802.11a/b/g, Bluetooth, Zig-Bee, various types of cordless phones, etc.
- Each transmitted signal can be characterized with
  - its spectra which are determined by the signal modulation format
  - its on/off sequence representing the signal activity in time
- Goal of the analysis is to estimate transmitter
  - its spectral occupancy
  - its activity sequence in time
  - its location in space

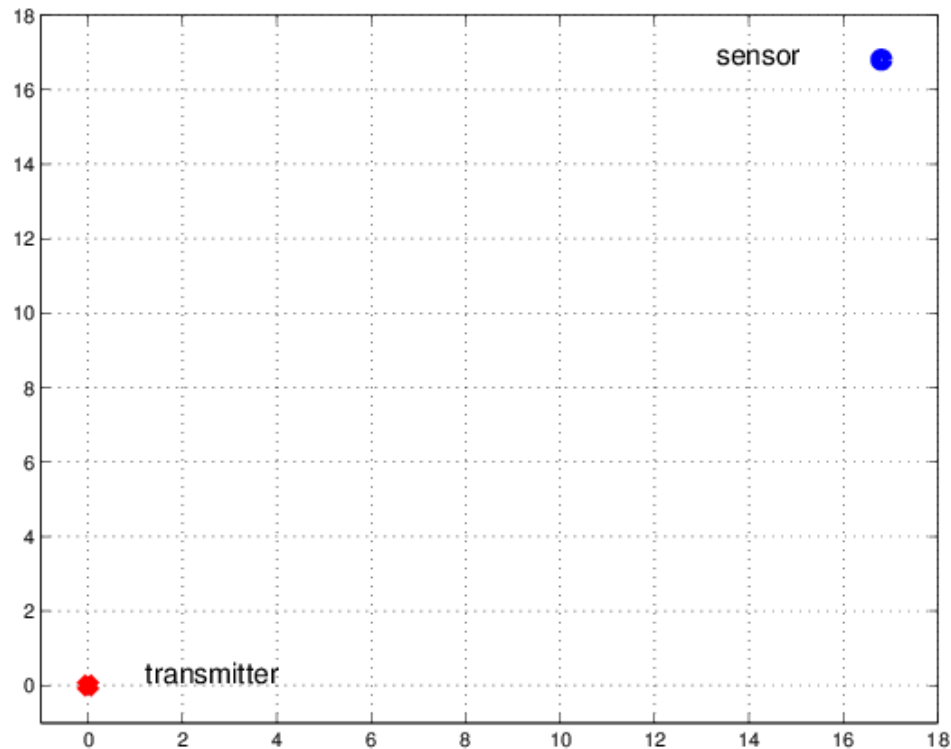
# Radio Scene Analysis for packet based radio signals

- Estimate
  - spectra
  - channels
  - on/off activity sequences
- Two stage algorithm
  - Signal segmentation
  - Fourth order spectrum based analysis

# Activity Segmentation via Mean Shift Analysis

- MSA segmentation algorithm localizes in time statistically homogeneous intervals in the received signal
- Segmented intervals may correspond to a transmission from zero, one, or more transmitters
- Similar intervals are clustered/segmented

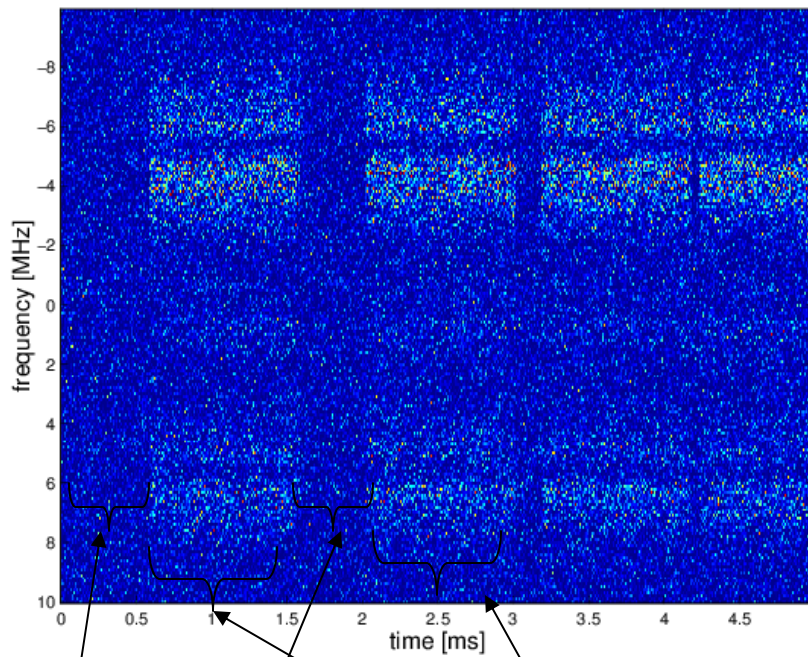
# Single Transmitter-Single Sensor Example



- One sensing node and one source transmitting DBPSK with Barker sequence spreading(802.11b at 1Mbit/sec)
- Measured channel transfer functions from(H. Kremo, et al. VTC '07)

# Spectra (Second Order Statistics) Clustering

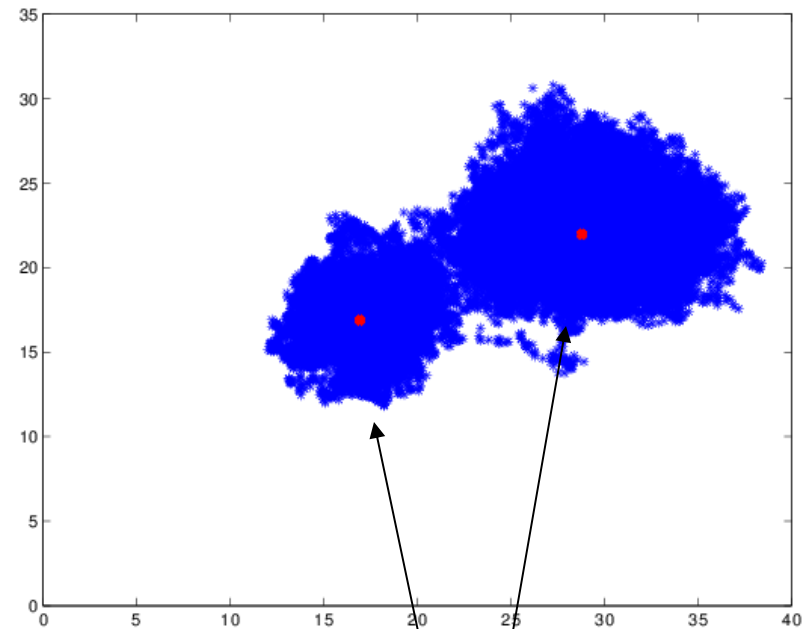
Spectrogram of the received signal ( $W=20\text{MHz}$ , total observation time 5 ms)



noise segments

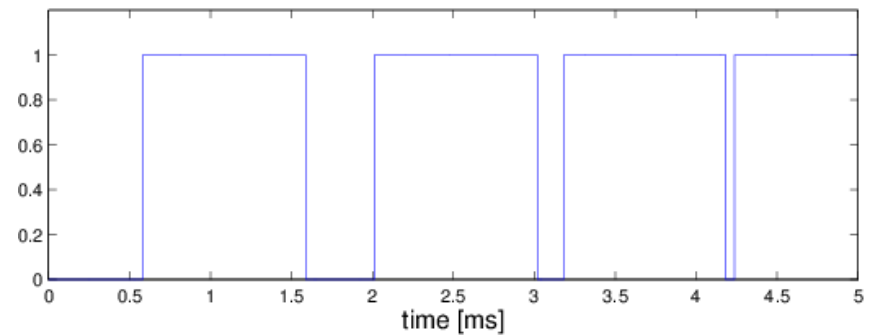
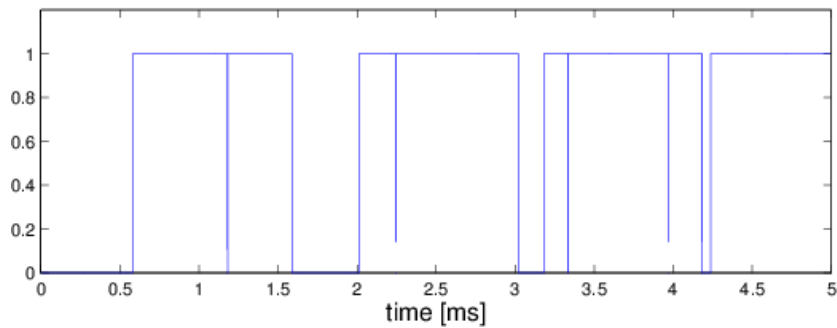
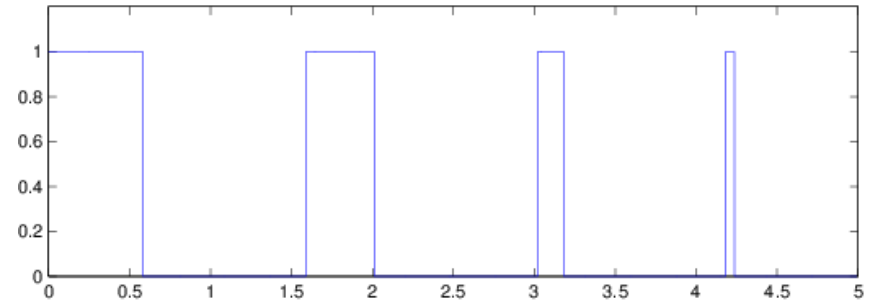
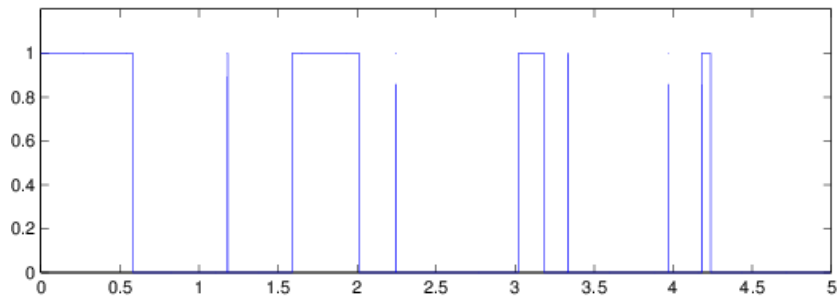
DBPSK signal plus noise segments (SNR=-3dB)

Scatter plot of the feature vectors  $\mathbf{x}_n$



There are two clusters

# Activity Segmentation and Impulse Noise Removal

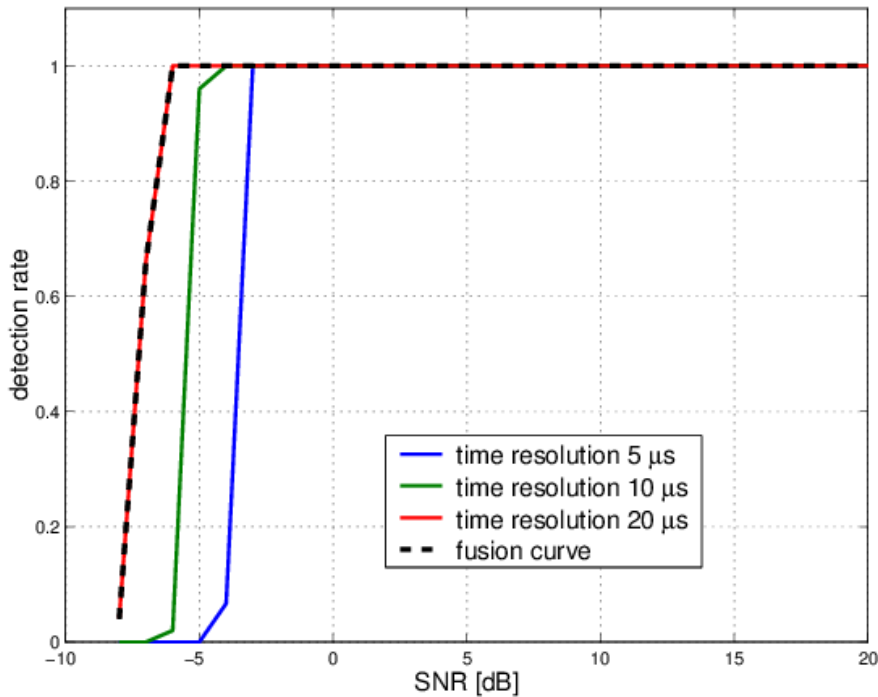


Segmentation results before  
impulse noise removal

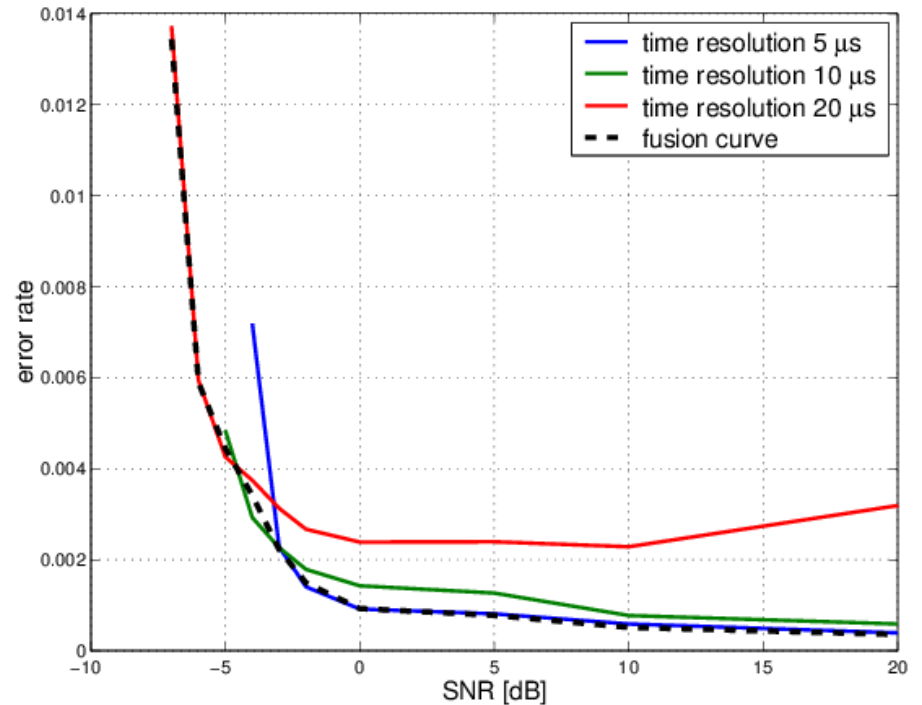
Segmentation results after  
impulse noise removal



# Multiresolution Segmentation Fusion



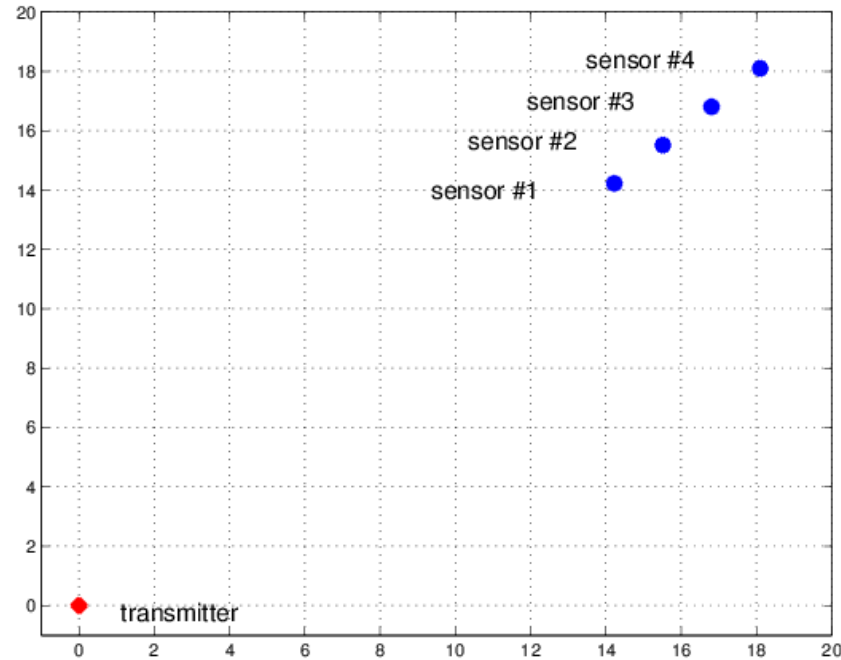
Detection rate of the correct number of clusters



Segmentation error rate

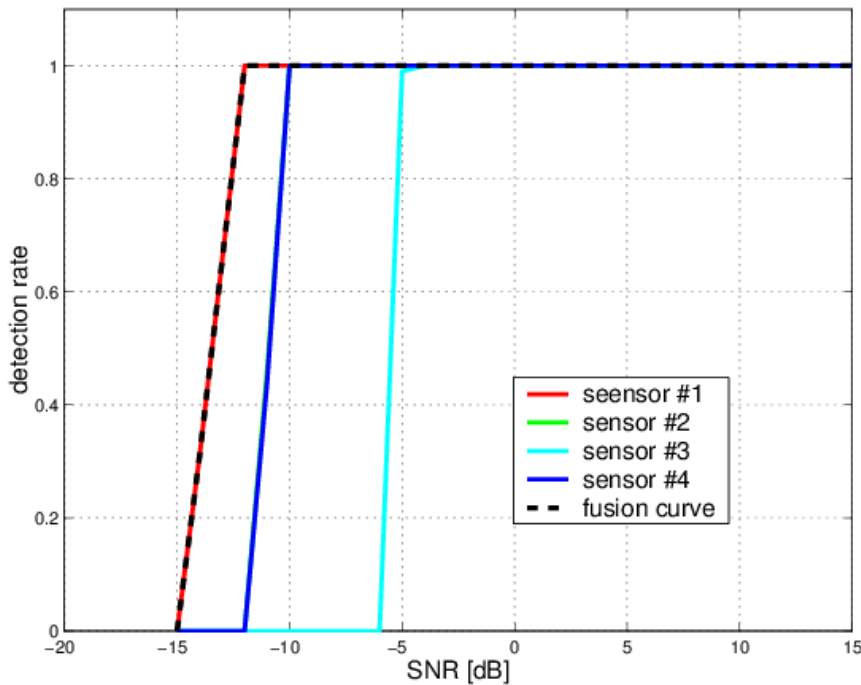
The algorithm is useful up to a threshold SNR

# Single Transmitter-Multiple Sensor Example: Collaborative Segmentation via Mean Shift Analysis

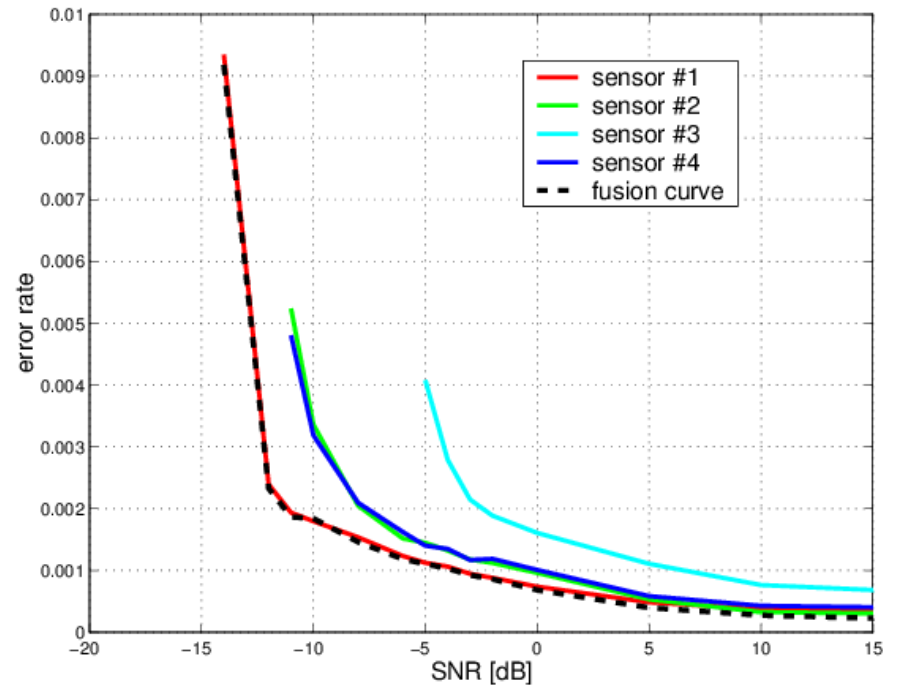


- Four sensing nodes and one source transmitting DBPSK with Barker sequence spreading(802.11b at 1Mbit/sec)
- Measured channel transfer functions from(H. Kremo, et al. VTC '07)

# Collaborative Segmentation Fusion



Detection rate of the correct number of clusters

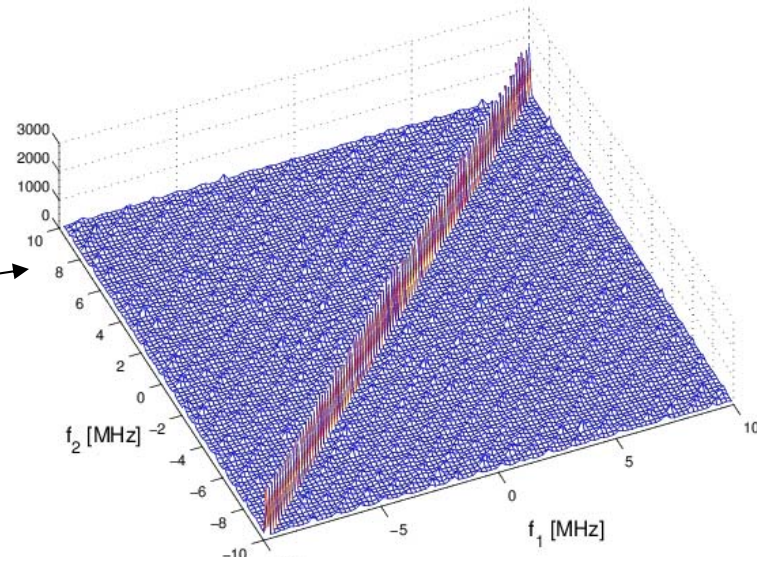
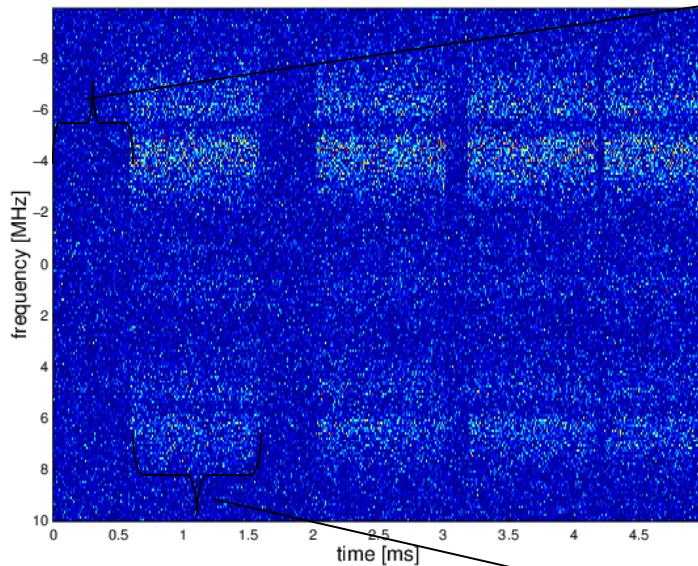


Segmentation error rate

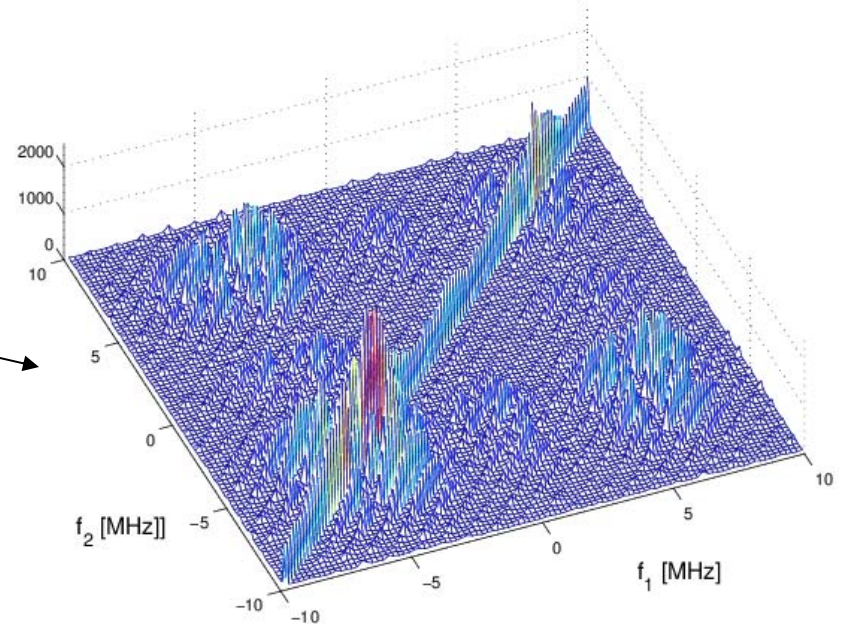
Fusion curves follow the sensor with the best SNR

# Beyond segmentation: signal analysis

Noise only segment: there is PSD and no cyclostationary spectra



DBPSK signal plus noise:  
There are cyclostationary  
spectra at  $f_1 - f_2 = k/T$  ( $T = 1 \mu\text{s}$ )

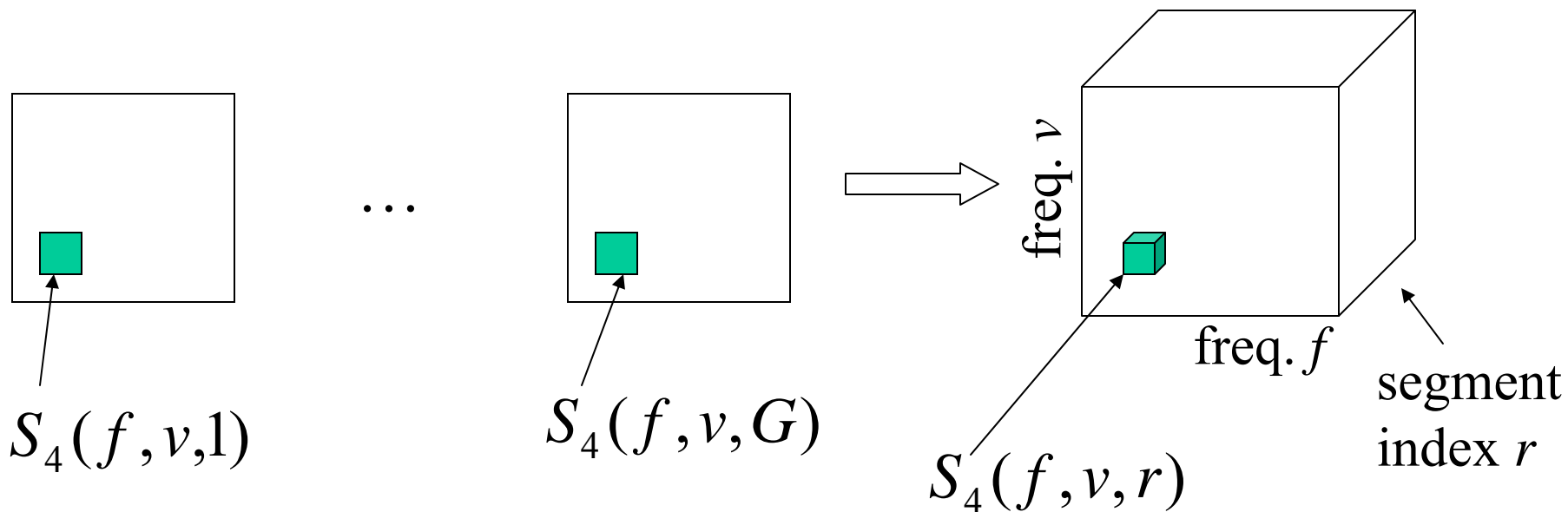


# Activity Segment Characterization: Fourth order spectrum (FOS) analysis

Characterizing transmissions over segments

- Determining transmission activity patterns for different possibly overlapping transmitters (blind source separation)
- Characterizing transmitter to sensor channels and/or spectra
- Characterizing transmitted spectra (blind deconvolution)

# Three-way array of FOS/trispectrum slices



$$S_4(f, \nu, r) = \sum_{p=1}^M |H_p(f)|^2 |H_p(\nu)|^2 S_{4p}(f, \nu) c_{rp} + S_N(f, \nu)$$

channel

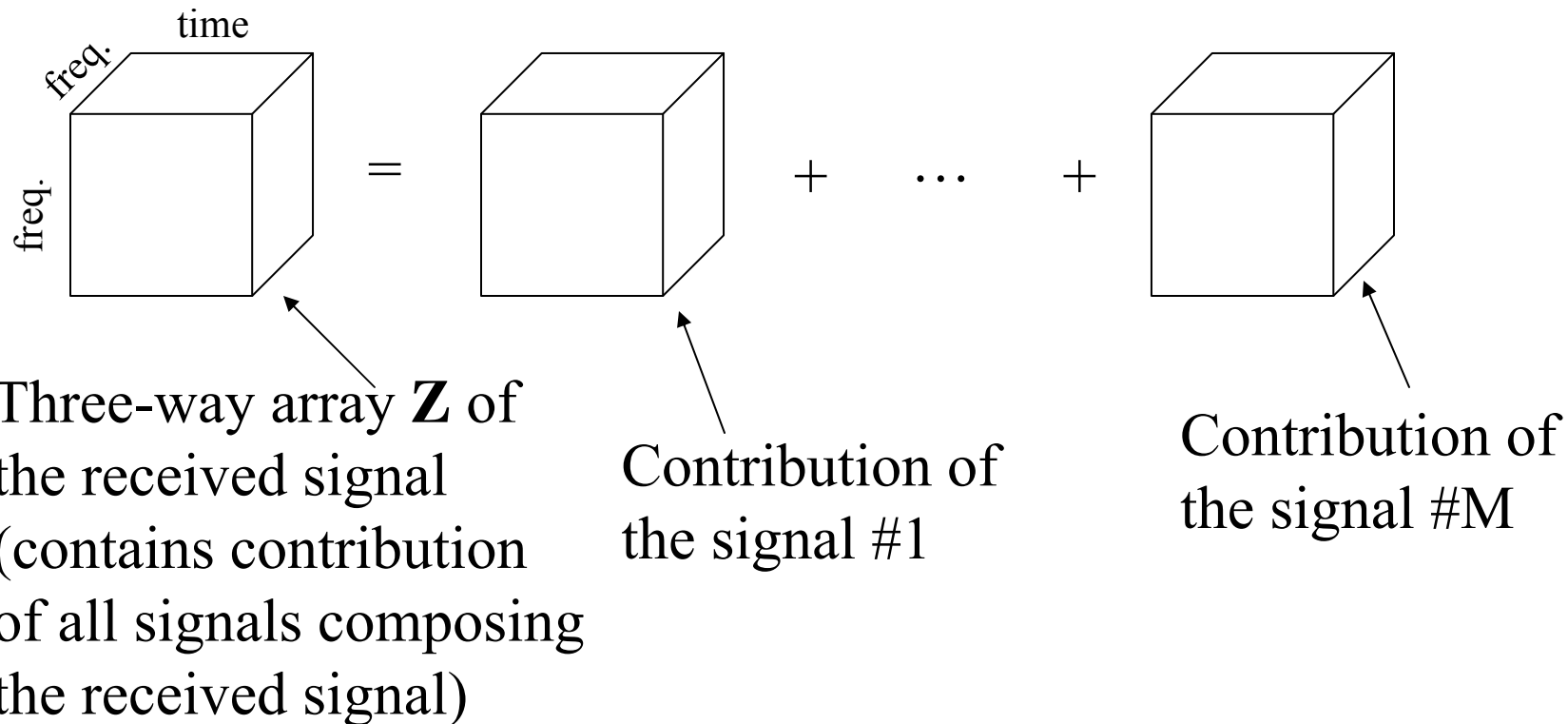
Tx Spectra

on/off sequence  
of the p-th source

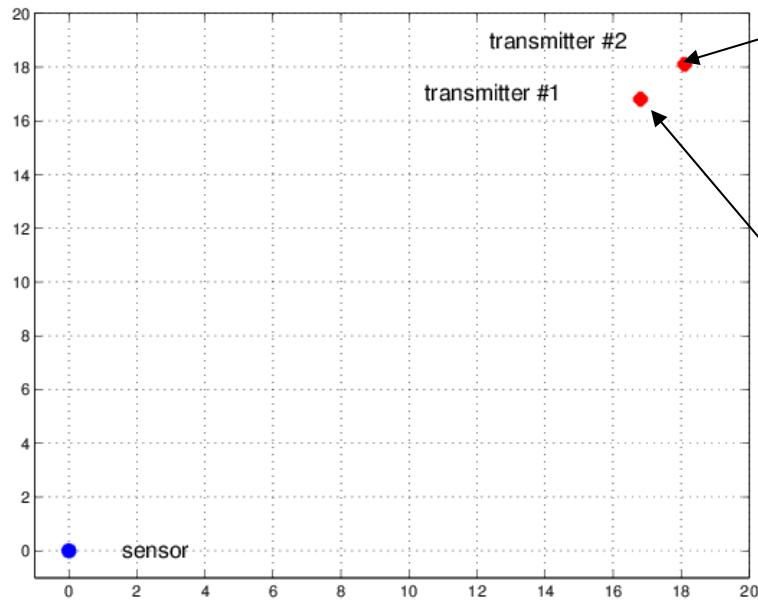
This is zero for  
Gaussian noise

# Tensor decomposition

- When the uniqueness conditions hold block terms representing contributions of individual signals can be *uniquely* recovered from  $\mathbf{Z}$



# Bluetooth vs 802.11b interference



One source transmitting GFSK signal with frequency hopping (Bluetooth)

One source transmitting DBPSK with Barker sequence spreading (802.11b)

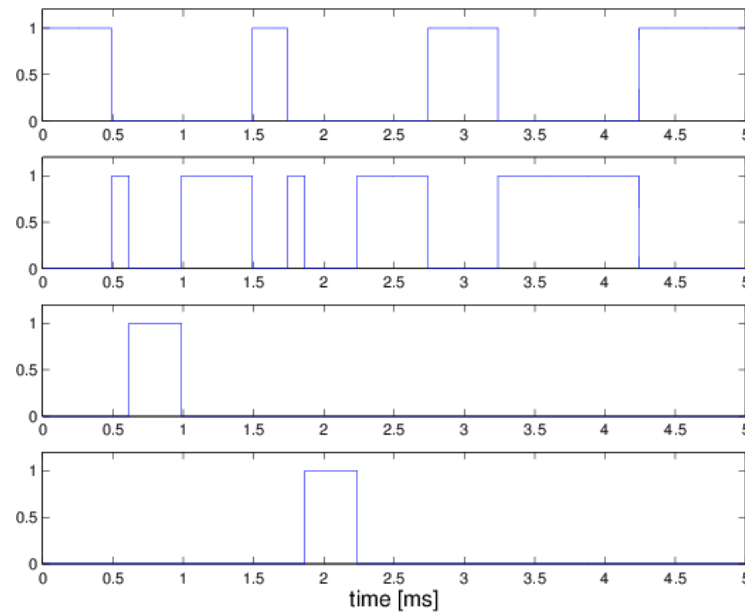
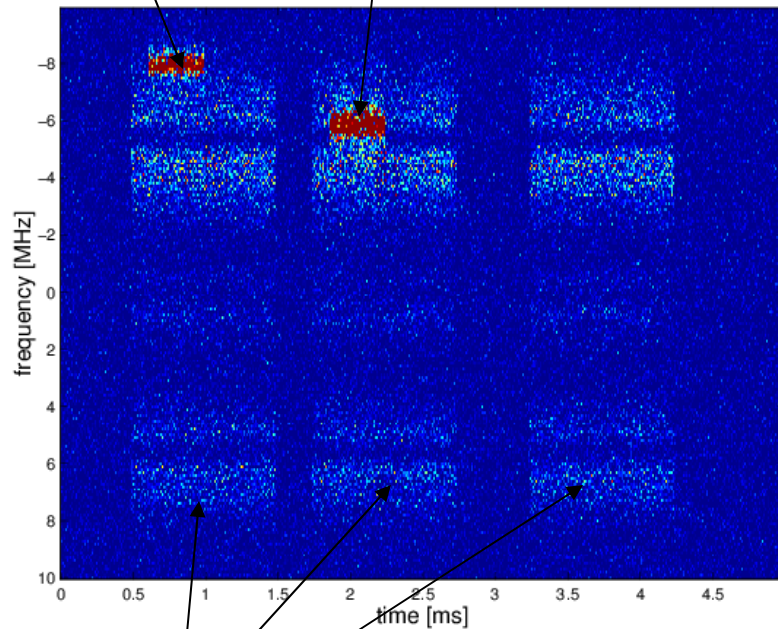
- One sensing node observes the 20MHz channel used by DBPSK transmitter
- Simulation uses the same measured channel transfer functions from(H. Kremo, et al. VTC '07)



# Mean Shift Segmentation

GSFK#1, SNR=5.7 dB

GSFK#2, SNR=10.5 dB

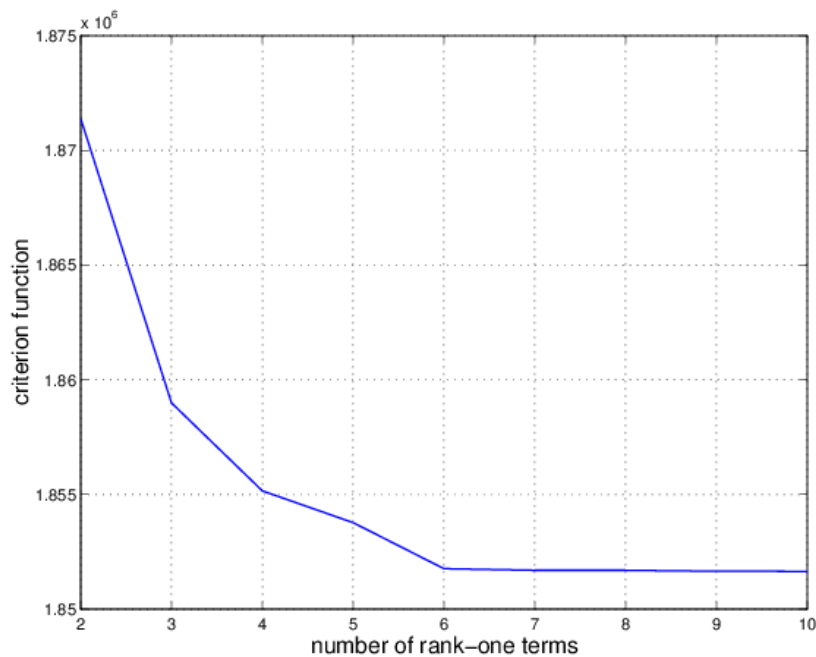


DBPSK, SNR=0 dB

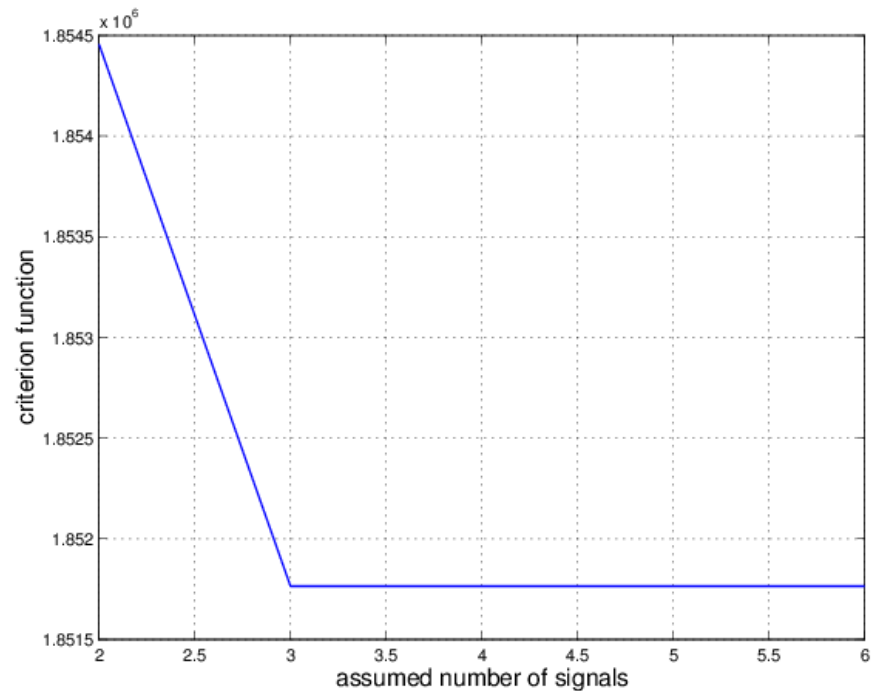
Spectrogram of the received signal  
W=20 MHz, total observation  
time 5 ms

Recovered segmentation  
sequences

# Finding the model parameters

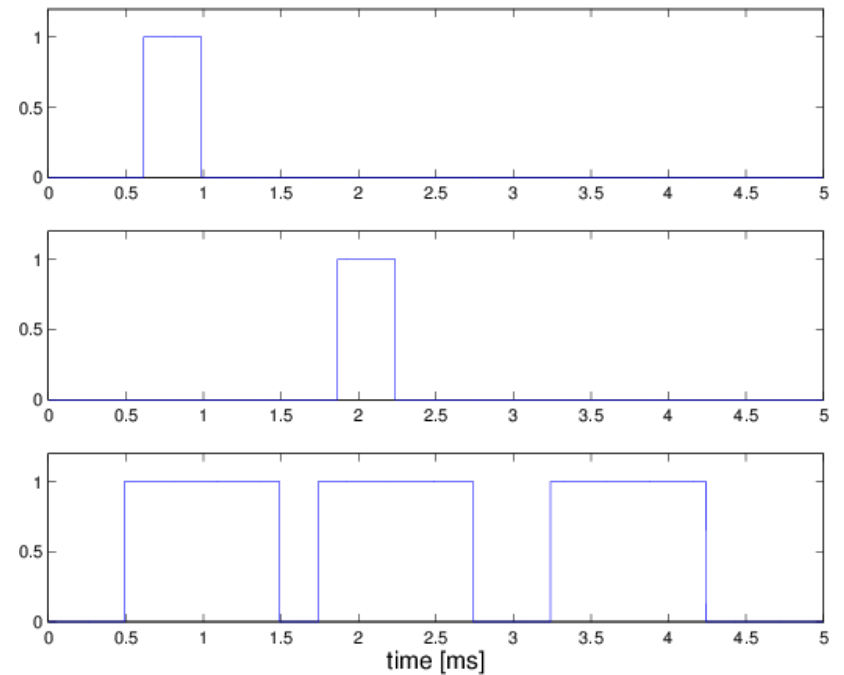
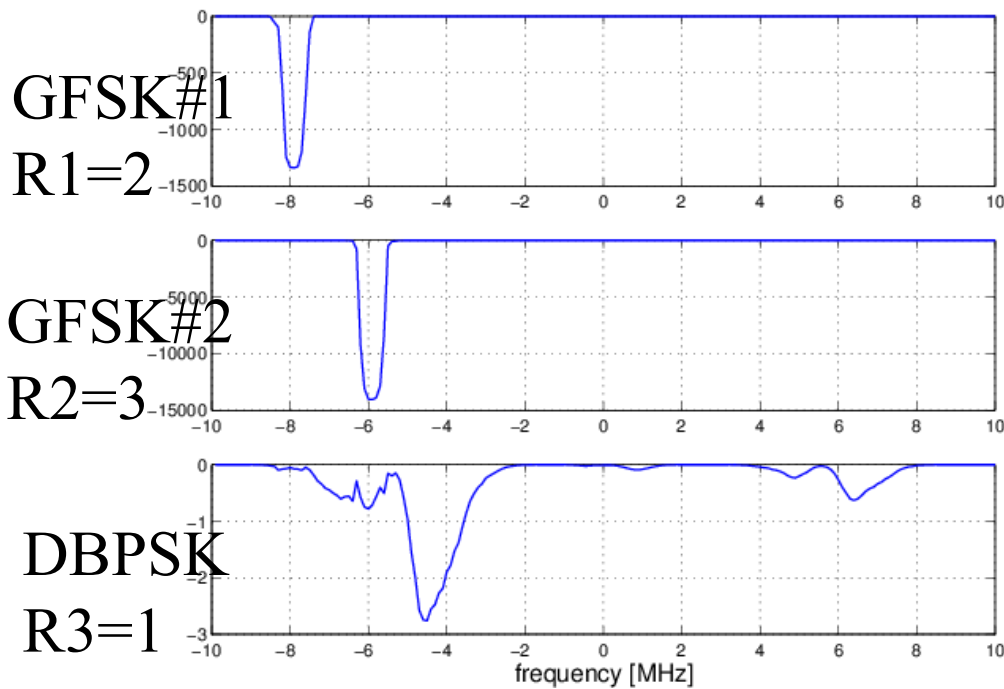


There are  $R=6$  rank-one terms



There are  $M=3$  signals

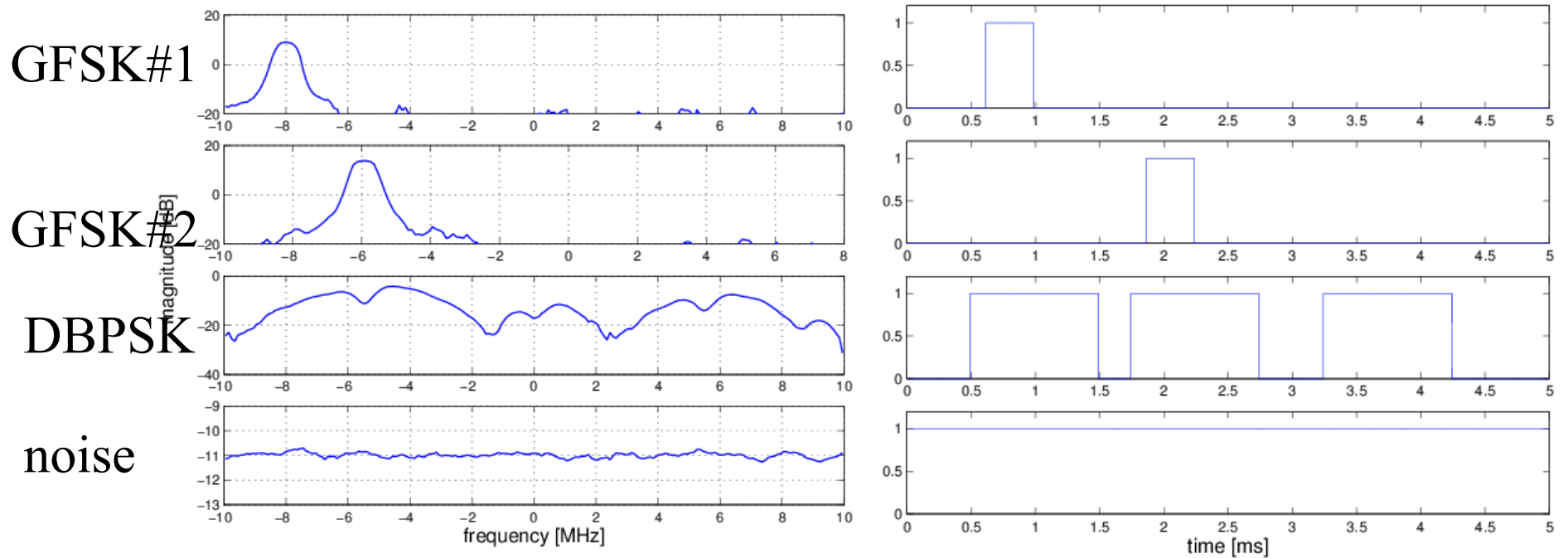
# FOS analysis results



Recovered diagonal entries of the  
FOS slices

Recovered activity sequences

# Recovered power spectra



# Conclusion

- We proposed an algorithm which estimates spectra and on/off activity sequences of packet based radio signals
- The algorithm consists of two steps:
  - Signal segmentation
  - Fourth order spectrum based analysis
- Performance limitations
  - Segmentation algorithm typically breaks down at some threshold SNR
  - FOS based analysis can recover only sufficiently strong signals or their rank-one terms
- When multiple sensors are available
  - single sensor performance limitations can be overcome
  - it is possible to localize identified transmitters in space

# Greedy Channel Surfing for Occupancy Analysis in Packet-Based Wireless Networks

Shridatt Sugrim

Advisors: Melike Baykal-Gursoy and Predrag Spasojevic