

A Practical Approach to Landmark Deployment for Indoor Localization

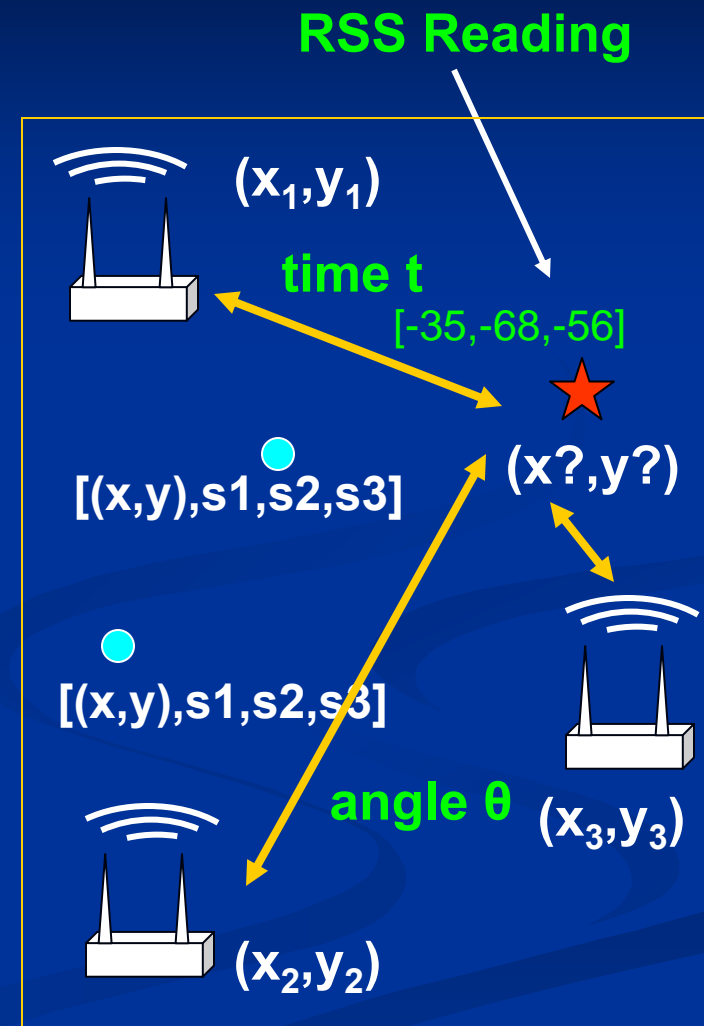
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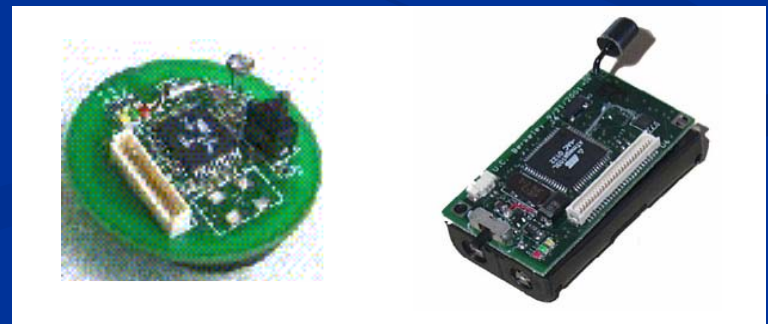
Background

- Transmit Packet at **unknown location**
- **Landmarks Rx**
- **Modality**
 - Received Signal Strength (RSS)
 - Time-Of-Arrival (TOA)
 - Angle-Of-Arrival (AOA)
- **Principle** to compute position
 - Lateration/Angulation
 - Scene matching
 - Training data/radio map
- Localization **results**



Motivation

- Localizing sensor nodes is a critical input for high-level networking applications:
 - Tracking, monitoring, and geometric-based routing
 - Location-based services become more prevalent
- Recent active research efforts have resulted in a plethora of localization methods.
- Study to improve the deployment of landmarks and thus help a wide variety of algorithms.



Contributions

- Impact of landmark placement on localization performance
 - Analytic Model
 - Experimental Results
- Compute **upper bound** on the maximum location error given the placement of landmarks.
- Find **optimal patterns** for landmark placement
 - Novel algorithm *maxL-minE*
- **Generic** analysis works for a variety of:
 - **algorithms, networks, and ranging modalities.**

Outline

- Background and motivation
- Theoretical Analysis
- Finding an Optimized Landmark Deployment
- Experimental Study
- Conclusion
- Related work

Analysis with Least Squares in Localization

- Ranging step:
 - Distance estimation between unknown and landmarks
 - Various methods available
 - Focus on RSS and TOA
- Lateration step:

$$(\hat{x}, \hat{y}) = \arg \min_{x,y} \sum_{i=1}^N [\sqrt{(x_i - x)^2 + (y_i - y)^2} - d_i]^2$$

- Traditional: Non-linear Least squares method

Error Analysis

- Reduce to Linear Least Squares: $\mathbf{Ax} = \mathbf{b}$

- Localization result: ideal

$$\mathbf{x} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{b}$$

- Localization result: actual

$$\tilde{\mathbf{x}} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \tilde{\mathbf{b}}$$

- Location estimation error:

$$\|\mathbf{x} - \tilde{\mathbf{x}}\| \leq \|\mathbf{A}^+\| \|\mathbf{e}\|$$

With $\tilde{\mathbf{b}} = \mathbf{b} + \mathbf{e}$

Error Analysis

The landmark deployments with equal eigenvalues

$\lambda_1 \cong \lambda_2$ minimize errors!

- $\|A^+\| = \frac{1}{\gamma_2}$, where $\gamma_1 \geq \gamma_2$ are the singular values of A
- The eigenvalues of $A^T A$ are the squares of the singular values of A
- The eigenvalues of $A^T A$ can be found as:

$$\lambda = 4(a + c) \pm 2\sqrt{(a - c)^2 + 4b^2}$$

$$a = \sum_{i=1}^N \left(x_i - \frac{1}{N} \sum_{i=1}^N x_i\right)^2$$

$$b = \sum_{i=1}^N \left[\left(x_i - \frac{1}{N} \sum_{i=1}^N x_i\right) \left(y_i - \frac{1}{N} \sum_{i=1}^N y_i\right)\right]$$

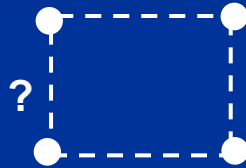
$$c = \sum_{i=1}^N \left(y_i - \frac{1}{N} \sum_{i=1}^N y_i\right)^2$$

Patterns for Optimal Landmark Placements

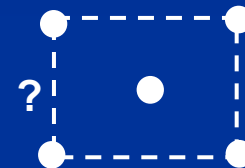
3 landmarks
(equilateral
triangle)



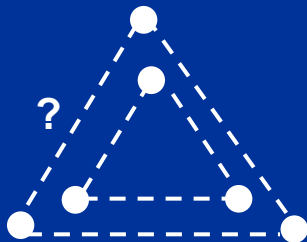
4 landmarks
(square)



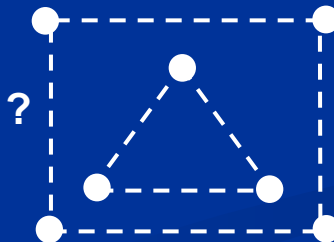
5 landmarks
(square plus
center of mass)



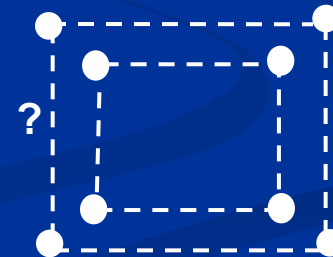
6 landmarks
(nested triangles)



7 landmarks
(square plus
nested triangle)



8 landmarks
(nested squares)



Finding the Optimal Deployment

- Analytic analysis gives us **shape**
- Length of sides unknown
- **Physical constrains** of a building
- ***MaxL-MinE*** Algorithm:
 - Get **optimal pattern** based on geometry
 - Fit optimal pattern into maximum floor size
 - **Stretch/shrink** the deployment shape until such movements stop reducing localization errors
 - An **iterative search** algorithm

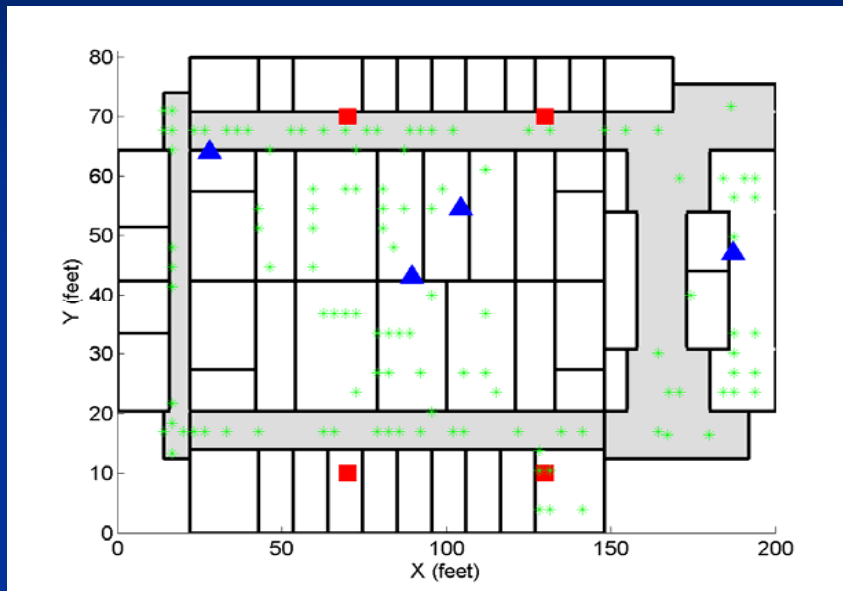
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- Finding an Optimized Landmark Deployment
- **Experimental Study**
- Conclusion
- Related work

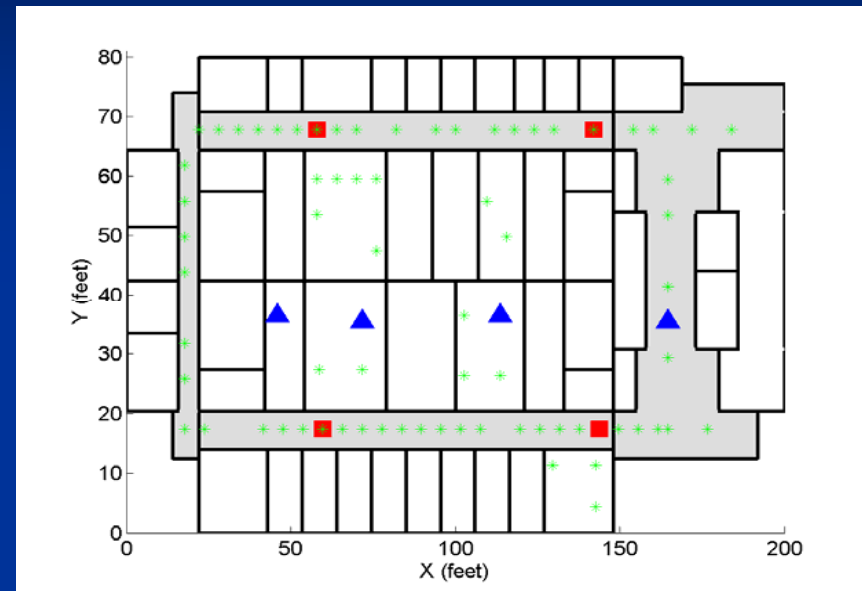
Experimental Study

- Networks:
 - 802.11 (WiFi)
 - 802.15.4 (ZigBee)
- Localization algorithms:
 - Point-based: RADAR
 - Area-based: ABP (Area Based Probability)
 - Lateration:
 - BN (Bayesian Networks)
 - LS (Least Squares)
- Ranging modalities:
 - RSS (Received Signal Strength)
 - TOA (Time of Arrival)

Experimental Setup



- 802.11 network
- 4 landmarks in two deployments:
 - Colinear case
 - Square case
- 115 training points



- 802.15.4 network
- 4 landmarks in two deployments:
 - Horizontal case
 - Square case
- 70 training points

Evaluation Metrics

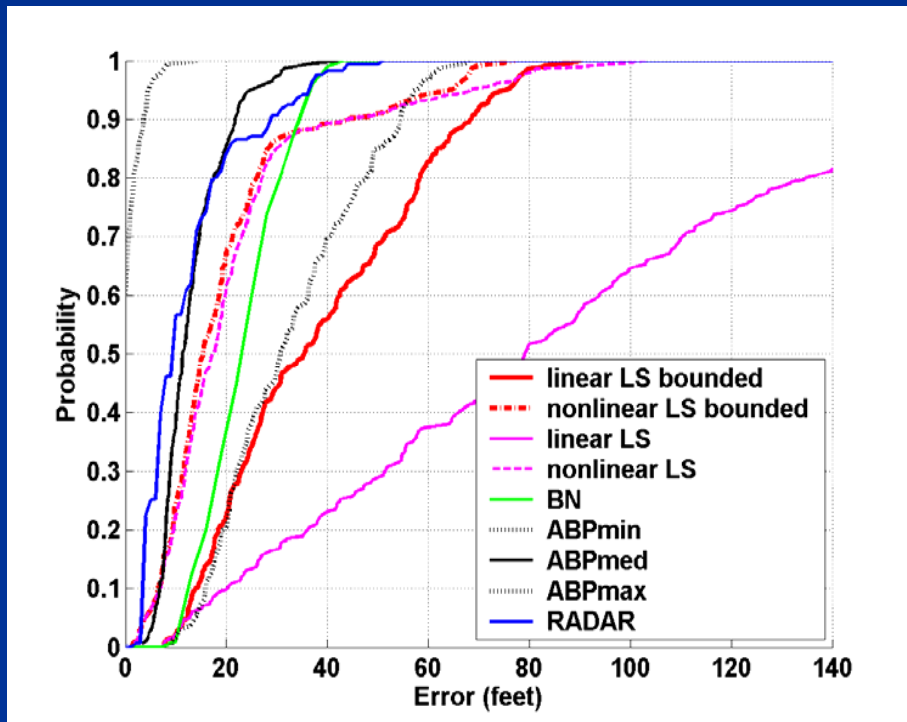
- **Error CDF**
 - Provide statistical specification of the localization accuracy
- **Average error**
 - Average of the distances between the estimated location to the true location
- **Hölder metrics**
 - Relates the magnitude of the perturbation in signal space to its effect on the localization results

$$H_{alg}^p = \max_{\mathbf{s}, \mathbf{v}} \frac{\|L_{alg}^p(\mathbf{s}) - L_{alg}^p(\mathbf{v})\|}{\|\mathbf{s} - \mathbf{v}\|}$$

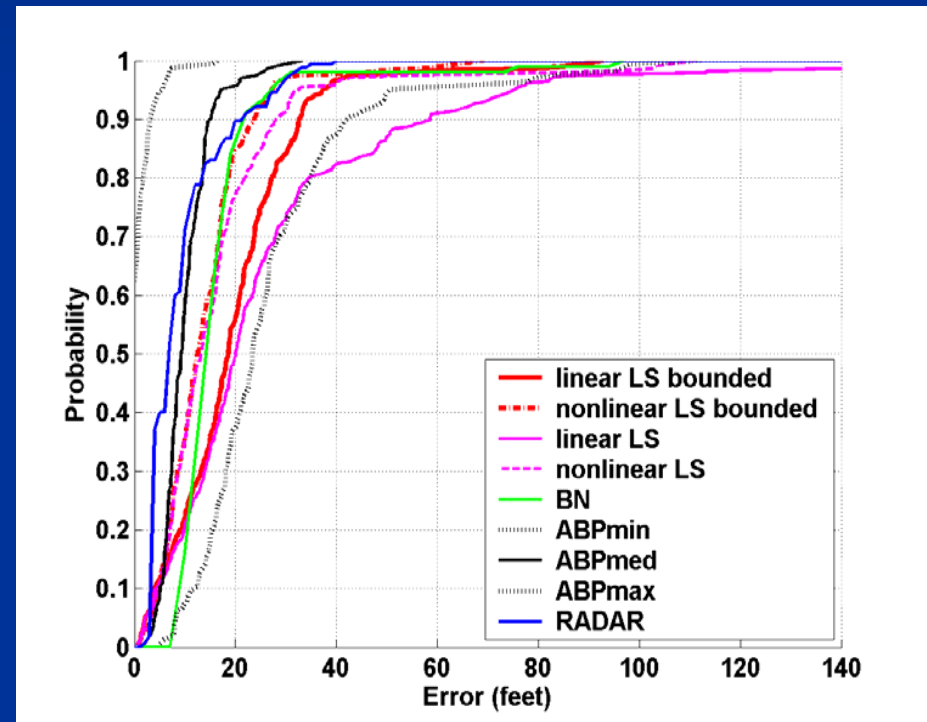
Localization Accuracy

RSS 802.11 Network

Error CDF across algorithms



Colinear case

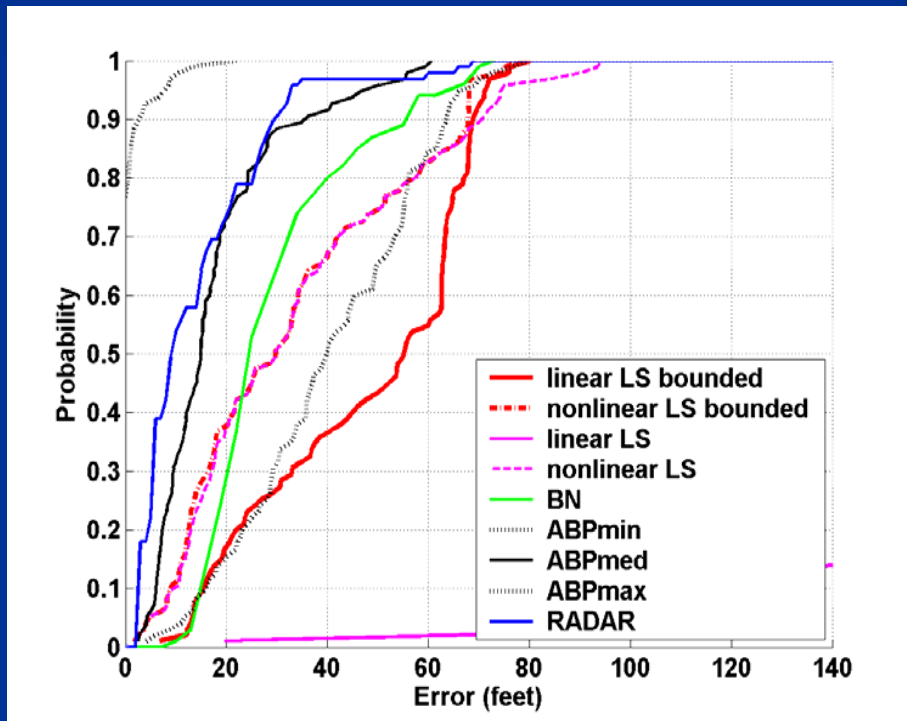


Square case

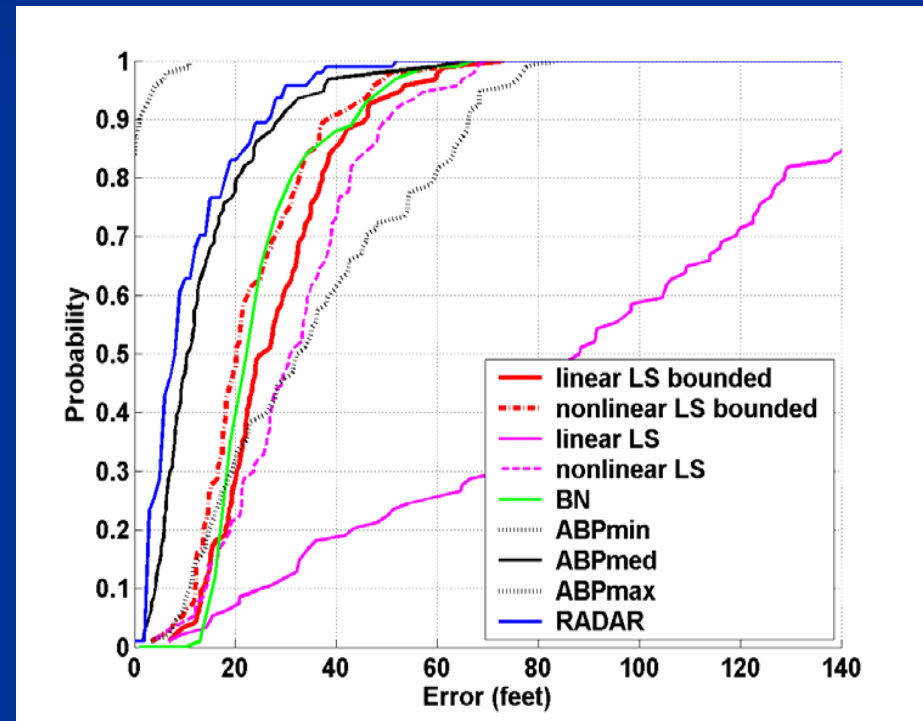
Localization Accuracy

RSS 802.15.4 Network

Error CDF across algorithms



Horizontal case

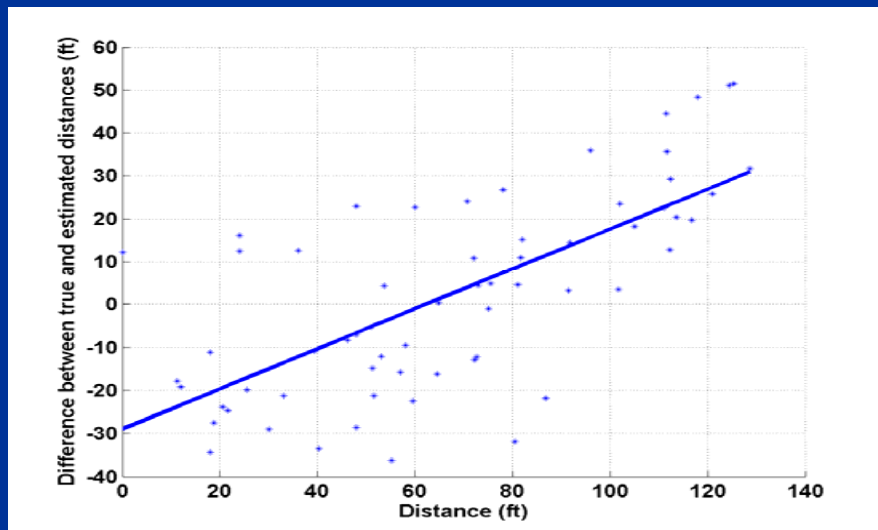


Square case

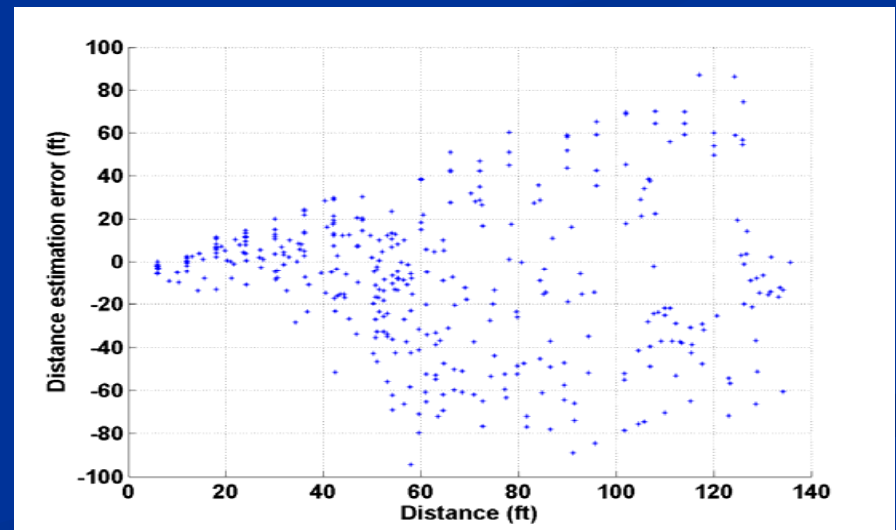
Using Time of Arrival

- Distance estimation based on round trip time between a node and a landmark
- Distance error analysis: TOA vs. RSS
- TOA error modeling:

$$\text{error} \sim N(\mu, \sigma^2) \text{ with } \hat{\mu} = b_0 + b_1 d_i \text{ and } \hat{\sigma}^2 = \frac{\sum_{i=1}^n (\tilde{d}_i - \hat{\mu})^2}{n-1}$$



TOA

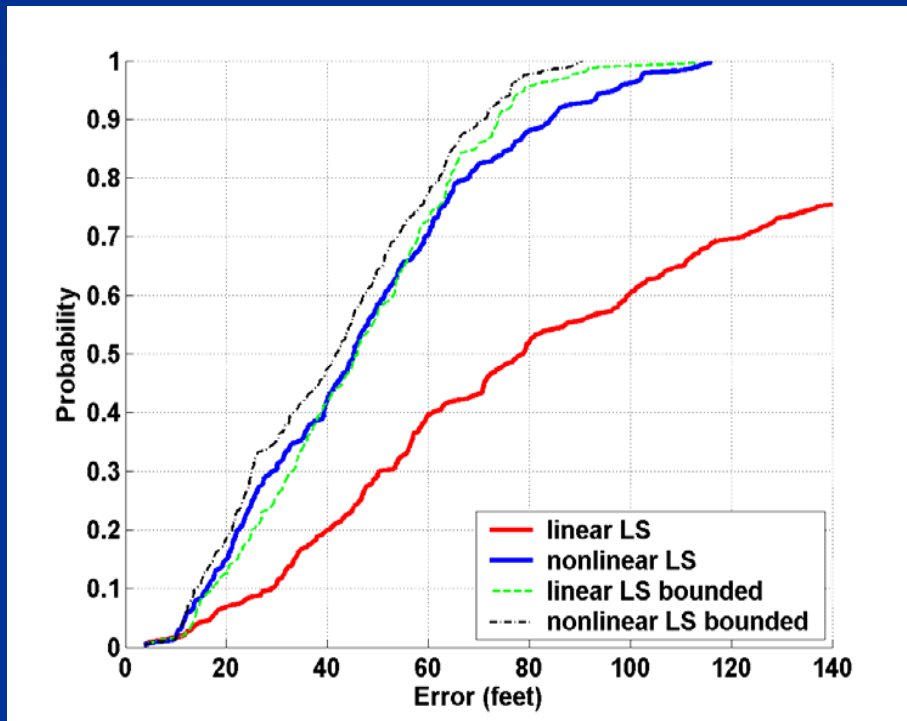


RSS

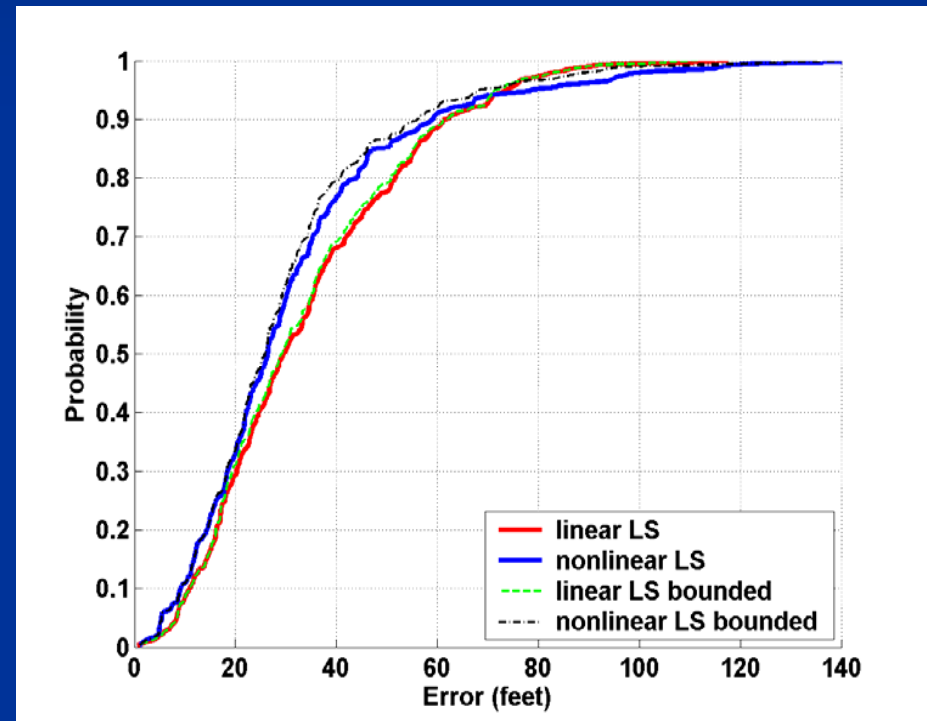
Localization Accuracy

TOA 802.11 Network

Error CDF across algorithms



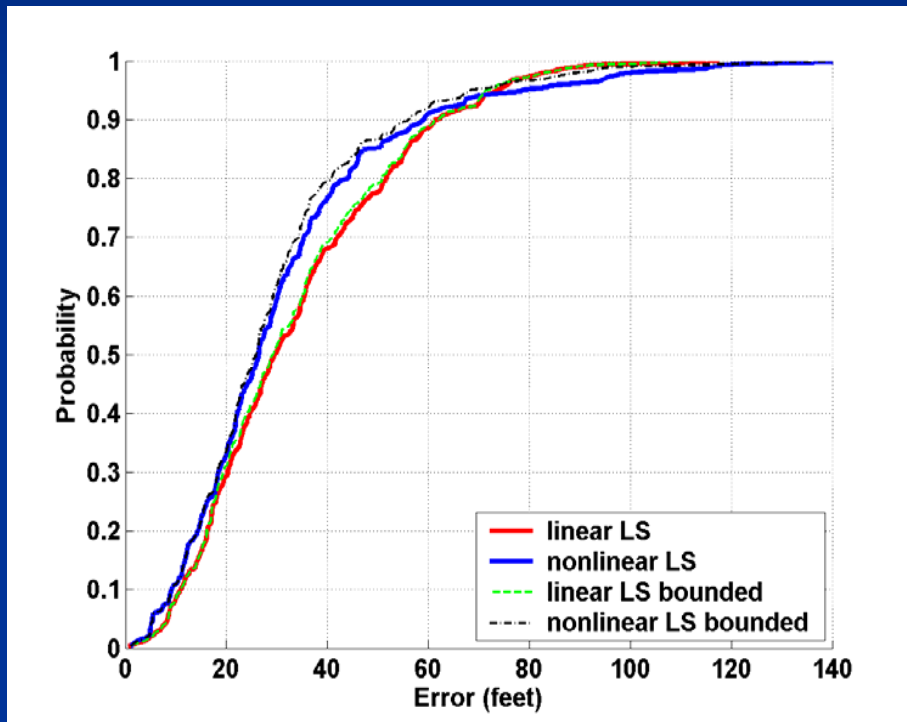
Colinear case



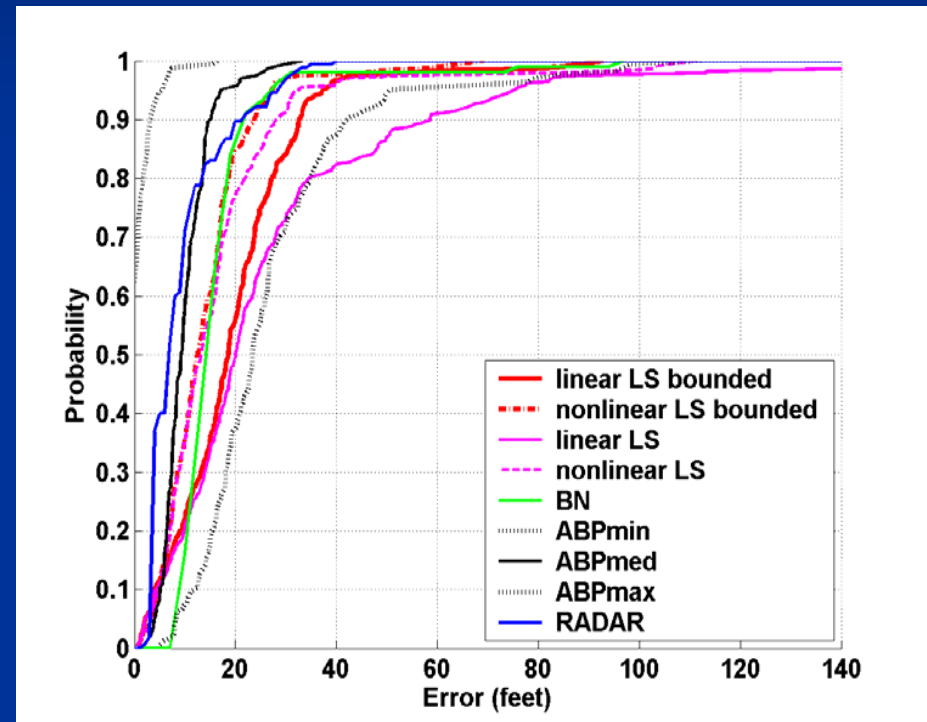
Square case

Localization Accuracy

Optimized landmark deployment



TOA



RSS

Conclusion

- Derived an upper bound on the maximum location error given the placement of landmarks
- Developed a novel algorithm, **maxL-minE**, for finding the optimal landmark placement
- Significant performance improvement of a wide variety of algorithms
 - ABP and RADAR: > 20%
 - LS: > 30%
 - BN: ~ 10%
- **Tension** between optimized landmark deployment for localization vs. deployments that optimize for signal coverage

Related Work

- Localization strategies:
 - Range-based [patwari05loc]: RSS [bahl00,elnahrawy04limits], TOA [GPS, toa04berlin] and TDOA [nissanka00]; or range-free [shang03, niculescu01aps]
 - Lateration [Langendoen03Survey, GPS, niculescu01aps, zang05robust, chinta04ad]; angulation; or scene-matching [youssef03localization, roos02stat, bahl00, elnahrawy04limits]
 - Aggregate [dohertyl01, shang03] or singular (only refer to landmarks)
- Study of AP deployment for localization:
 - Simulation to study the location error and signal strength model for a few AP configurations [chen02signal]
 - Developed a set of heuristic search algorithms to find optimal AP deployment [battiti03optimal]
 - examined placement, but did not find optimal solutions [krish05accuracy]
- Network signal coverage perspective:
 - AP placement to maximize coverage and throughput properties of wireless LANs and sensor networks

Thank you & Questions